Decision Procedures in Verification

Combinations of decision procedures (4)

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Until now:

Logical Theories: generalities

- Theory of Uninterpreted Function Symbols
- Decision procedures for numeric domains

  Difference logic

  Linear arithmetic: Fourier-Motzkin
- Combinations of decision procedures

  Definitions

  The Nelson/Oppen Procedure

  DPLL(T)

  A theory of arrays

Satisfiability of formulae with quantifiers

In many applications we are interested in testing the satisfiability of formulae containing (universally quantified) variables.

Examples

- check satisfiability of formulae in the Bernays-Schönfinkel class
- check whether a set of (universally quantified) Horn clauses entails a ground clause
- check whether a property is consequence of a set of axioms

  Example 1: $f : \mathbb{Z} \to \mathbb{Z}$ is monotonely increasing
  and $g : \mathbb{Z} \to \mathbb{Z}$ is defined by $g(x) = f(x + x)$
  then g is also monotonely increasing

  Example 2: If array a is increasingly sorted, and
  x is inserted before the first position i with $a[i] > x$
  then the array remains increasingly sorted.

A theory of arrays

We consider the theory of arrays in a many-sorted setting.

Syntax:

- Sorts: Elem (elements), Array (arrays) and Index (indices, here integers).
- Function symbols: read, write.

  $a(\text{read}) = \mathit{Array} \times \mathit{Index} \to \mathit{Element}$

  $a(\text{write}) = \mathit{Array} \times \mathit{Index} \times \mathit{Element} \to \mathit{Array}$

Theories of arrays

We consider the theory of arrays in a many-sorted setting.

Theory of arrays $\mathcal{T}_{arrays}$:

- $\mathcal{T}_i$ (theory of indices): Presburger arithmetic
- $\mathcal{T}_e$ (theory of elements): arbitrary
- Axioms for read, write

$$\begin{aligned} read(write(a, i, e), i) &\approx e \\ j \not\approx i \vee read(write(a, i, e), j) &= read(a, j). \end{aligned}$$

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Fact: Undecidable in general.

Goal: Identify a fragment of the theory of arrays which is decidable.

A decidable fragment

- **Index guard** a positive Boolean combination of atoms of the form $t \leq u$ or $t = u$ where t and u are either a variable or a ground term of sort Index

  Example: $(x \leq 3 \vee x \approx y) \wedge y \leq z$ is an index guard

  $x \leq c - 1$ (where c is a constant) is an index guard

  Example: $x + 1 \leq y$, $x + 3 \leq y - 1$, $x + x \leq 2$ are not index guards.

- **Array property formula** [Bradley,Manna,Sipma'06]

  $(\forall i)(\varphi_I(i) \rightarrow \varphi_V(i))$, where:

  φ_I: index guard

  φ_V: formula in which any universally quantified i occurs in a direct array read; no nestings

  Example: $c \leq x \leq y \leq d \rightarrow a(x) \leq a(y)$ is an array property formula

  Example: $x < y \rightarrow a(x) < a(y)$ is not an array property formula

Decision Procedure

(Rules should be read from top to bottom)

Step 1: Put F in NNF.

Step 2: Apply the following rule exhaustively to remove writes:

$$\frac{F[\mathit{write}(a, i, v)]}{F[a'] \wedge a'[i] = v \wedge (\forall j.j \neq i \rightarrow a[j] = a'[j])} \quad \text{for fresh } a' \text{ (write)}$$

Given a formula F containing an occurrence of a write term $\mathit{write}(a, i, v)$, we can substitute every occurrence of $\mathit{write}(a, i, v)$ with a fresh variable a' and explain the relationship between a' and a.

Decision Procedure

Step 3 Apply the following rule exhaustively to remove existential quantification:

$$\frac{F[\exists i.G[i]]}{F[G[j]]} \text{ for fresh } j \text{ (exists)}$$

Existential quantification can arise during Step 1 if the given formula contains a negated array property.

Decision Procedure

Steps 4-6 accomplish the reduction of universal quantification to finite conjunction.

The main idea is to select a set of symbolic index terms on which to instantiate all universal quantifiers.

Theories of arrays

Step 4 From the output F3 of Step 3, construct the index set $\mathcal{I}$:

$$\begin{aligned}\mathcal{I} \quad = \quad & \{\lambda\} \cup \\ & \{t \mid \cdot[t] \in F3 \text{ such that } t \text{ is not a universally quantified variable}\} \cup \\ & \{t \mid t \text{ occurs as a ground term in the parsing of index guards}\}\end{aligned}$$

This index set is the finite set of indices that need to be examined. It includes all ground terms t that occur in some $\mathit{read}(a, t)$ anywhere in F and all ground terms t that are compared to a universally quantified variable in some index guard.

λ is a fresh constant that represents all other index positions that are not explicitly in $\mathcal{I}$.

Theories of arrays

Step 5 Apply the following rule exhaustively to remove universal quantification:

$$\frac{H[\forall \bar{i}.F[i] \to G[i]]}{H\left[\bigwedge_{\bar{i} \in \mathcal{I}^n} (F[\bar{i}] \to G[\bar{i}])\right]} \quad \text{(forall)}$$

where n is the size of the list of quantified variables $\bar{i}$.

This is the key step.

It replaces universal quantification with finite conjunction over the index set. The notation $\bar{i} \in \mathcal{I}^n$ means that the variables $\bar{i}$ range over all n-tuples of terms in $\mathcal{I}$.

Theories of arrays

Step 6: From the output $F5$ of Step 5, construct

$$F6: \qquad F5 \wedge \bigwedge_{i \in \mathcal{I} \setminus \{\lambda\}} \lambda \neq i$$

The new conjuncts assert that the variable λ introduced in Step 4 is unique: it does not equal any other index mentioned in F5.

Step 7: Decide the TA-satisfiability of $F6$ using the decision procedure for the quantifier free fragment.

Example

Consider the array property formula

$$F : write(a, l, v)[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\forall i.i \neq l \rightarrow a[i] = b[i])$$

It contains one array property,

$$\forall i.i \neq l \rightarrow a[i] = b[i]$$

index guard: $i \neq l \equiv (i \leq l - 1 \vee i \geq l + 1)$ value constraint: $a[i] = b[i]$

Step 1: The formula is already in NNF.

Step 2: We rewrite F as:

$$F2 : \quad a'[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\forall i.i \neq l \rightarrow a[i] = b[i])$$
$$\wedge a'[l] = v \wedge (\forall j.j \neq l \rightarrow a[j] = a'[j]).$$

Example

Consider the array property formula

$$F : write(a, l, v)[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\forall i.i \neq l \rightarrow a[i] = b[i])$$

Step 2: We rewrite F as:

$$F2 : \quad a'[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\forall i.i \neq l \rightarrow a[i] = b[i]) \wedge a'[l] = v \wedge (\forall j.j \neq l \rightarrow a[j] = a'[j]).$$

Step 3: F2 does not contain any existential quantifiers $\mapsto$ F3 = F2.

Step 4: The index set is

$$\mathcal{I} = \{\lambda\} \cup \{k\} \cup \{l, l-1, l+1\} = \{\lambda, k, l, l-1, l+1\}$$

Example

Consider the array property formula

$$F : write(a, l, v)[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\forall i.i \neq l \rightarrow a[i] = b[i])$$

Step 3:

$$F3 : \quad a'[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\forall i.i \neq l \rightarrow a[i] = b[i])$$
$$\wedge a'[l] = v \wedge (\forall j.j \neq l \rightarrow a[j] = a'[j]).$$

Step 4: $\mathcal{I} = \{\lambda\} \cup \{k\} \cup \{l, l-1, l+1\} = \{\lambda, k, l, l-1, l+1\}$

Step 5: we replace universal quantification as follows:

$$F5 : \quad a'[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge \bigwedge_{i \in \mathcal{I}} (i \neq l \rightarrow a[i] = b[i])$$
$$\wedge a'[l] = v \wedge \bigwedge_{i \in \mathcal{I}} (j \neq l \rightarrow a[j] = a'[j]).$$

Example

Consider the array property formula

$$F : write(a, l, v)[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\forall i.i \neq l \rightarrow a[i] = b[i])$$

$$\mathcal{I} = \{\lambda\} \cup \{k\} \cup \{l, l-1, l+1\} = \{\lambda, k, l, l-1, l+1\}$$

Step 5 (continued) Expanding produces:

$$\begin{aligned} F5' : \quad & a'[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\lambda \neq l \rightarrow a[\lambda] = b[\lambda]) \\ & \wedge (k \neq l \rightarrow a[k] = b[k]) \wedge (l \neq l \rightarrow a[l] = b[l]) \wedge (l \neq l \pm 1 \rightarrow a[l \pm 1] = b[l \pm 1]) \\ & \wedge a'[l] = v \wedge (\lambda \neq l \rightarrow a[\lambda] = a'[\lambda]) \wedge (k \neq l \rightarrow a[k] = a'[k]) \\ & \wedge (l \neq l \rightarrow a[l] = a'[l]) \wedge (l \neq l \pm 1 \rightarrow a[l \pm 1] = a'[l \pm 1]). \end{aligned}$$

Example

Consider the array property formula

$$F : write(a, l, v)[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\forall i.i \neq l \rightarrow a[i] = b[i])$$

$$\mathcal{I} = \{\lambda\} \cup \{k\} \cup \{l, l-1, l+1\} = \{\lambda, k, l, l-1, l+1\}$$

Step 5 (continued): Simplifying produces

$$\begin{aligned} F''5 : \quad & a'[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\lambda \neq l \rightarrow a[\lambda] = b[\lambda]) \\ & \wedge (k \neq l \rightarrow a[k] = b[k]) \wedge a[l+1] = b[l+1] \wedge a[l-1] = b[l-1] \\ & \wedge a'[l] = v \wedge (\lambda \neq l \rightarrow a[\lambda] = a'[\lambda]) \\ & \wedge (k \neq l \rightarrow a[k] = a'[k]) \wedge a[l-1] = a'[l-1] \wedge a[l+1] = a'[l+1]. \end{aligned}$$

Example

Consider the array property formula

$$F : write(a, l, v)[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\forall i.i \neq l \rightarrow a[i] = b[i])$$

Step 6 distinguishes λ from other members of $\mathbf{I}$:

$$\begin{aligned} F6 : \quad & a'[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\lambda \neq l \rightarrow a[\lambda] = b[\lambda]) \\ & \wedge (k \neq l \rightarrow a[k] = b[k]) \wedge a[l+1] = b[l+1] \wedge a[l-1] = b[l-1] \\ & \wedge a'[l] = v \wedge (\lambda \neq l \rightarrow a[\lambda] = a'[\lambda]) \\ & \wedge (k \neq l \rightarrow a[k] = a'[k]) \wedge a[l+1] = a'[l+1] \wedge a[l-1] = a'[l-1] \\ & \wedge \lambda \neq k \wedge \lambda \neq l \wedge \lambda \neq l-1 \wedge \lambda \neq l+1. \end{aligned}$$

Example

Consider the array property formula

$$F : write(a, l, v)[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\forall i.i \neq l \rightarrow a[i] = b[i])$$

Step 6 Simplifying, we have

$$\begin{aligned} F'6 : \quad & a'[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge a[\lambda] = b[\lambda] \\ & \wedge (k \neq l \rightarrow a[k] = b[k]) \wedge a[l+1] = b[l+1] \wedge a[l-1] = b[l-1] \\ & \wedge a'[l] = v \wedge a[\lambda] = a'[\lambda] \\ & \wedge (k \neq l \rightarrow a[k] = a'[k]) \wedge a[l+1] = a'[l+1] \wedge a[l-1] = a'[l-1] \\ & \wedge \lambda \neq k \wedge \lambda \neq l \wedge \lambda \neq l+1 \wedge \lambda \neq l-1. \end{aligned}$$

There are two cases to consider.

(1) If $k{=}l$, then $a'[l]{=}v$ and $a'[k]{=}b[k]$ imply $b[k]{=}v$, yet $b[k]{\neq}v$.

(2) If $k{\neq}l$, then $a[k]{=}v$ and $a[k]{=}b[k]$ imply $b[k]{=}v$, but again $b[k]{\neq}v$.

Hence, F'6 is TA-unsatisfiable, indicating that F is TA-unsatisfiable.

Soundness and Completeness

Theorem (Soundness and Completeness)

Consider a formula F from the array property fragment . The output F6 of Step 6 is T_{arrays}-equisatisfiable to F.

Proof

(Soundness) Step 1-6 preserve satisfiability

(Fi is a logical consequence of F$i-1$).

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Proof (Completeness)

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Assume that $F6$ is satisfiabile. Clearly F5 has a model.

Soundness and Completeness

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Proof (Completeness)

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Assume that $F5$ is satisfiabile. Let $\mathcal{A} = (\mathbb{Z}, \text{Elem}, \{a_A\}_{a \in Arrays}, ...)$ be a model for F5. Construct a model $\mathcal{B}$ for $F4$ as follows.

For $x \in \mathbb{Z}$: $l(x)$ ($u(x)$) closest left (right) neighbor of x in $\mathcal{I}$.

$$a_{\mathcal{B}}(x) = \begin{cases} a_{\mathcal{A}}(l(x)) & \text{if } x - l(x) \leq u(x) - x \text{ or } u(x) = \infty \\ a_{\mathcal{A}}(u(x)) & \text{if } x - l(x) > u(x) - x \text{ or } l(x) = -\infty \end{cases}$$

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If F3 has model then F2 has model

Soundness and Completeness

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Given a formula F containing an occurrence of a write term $write(a, i, v)$, we can substitute every occurrence of $write(a, i, v)$ with a fresh variable a' and explan the relationship between a' and a.

If F2 has a model then F1 has a model.

Step 1: Put F in NNF: NNF F1 is equivalent to F.

Theories of arrays

Theorem (Complexity) Suppose $(T_{index} \cup T_{elem})$-satisfiability is in NP. For sub-fragments of the array property fragment in which formulae have bounded-size blocks of quantifiers, T_{arrays}-satisfiability is NP-complete.

Proof NP-hardness is clear.

That the problem is in NP follows easily from the procedure: instantiating a block of n universal quantifiers quantifying subformula G over index set I produces $|I| \cdot n$ new subformulae, each of length polynomial in the length of G. Hence, the output of Step 6 is of length only a polynomial factor greater than the input to the procedure for fixed n.

Program verification

Example: Does BubbleSort return a sorted array?

```
int [] BubbleSort(int[] a) {
    int i, j, t;
    for (i := |a| − 1; i > 0; i := i − 1) {
        for (j := 0; j < i; j := j + 1) {
            if (a[j] > a[j + 1]){t := a[j];
                                 a[j] := a[j + 1];
                                 a[j + 1] := t};
}} return a}
```

Program Verification

$-1 \leq i < |a| \wedge$
$\text{partitioned}(a, 0, i, i+1, |a|-1) \wedge$
$\text{sorted}(a, i, |a|-1)$

$-1 \leq i < |a| \wedge 0 \leq j \leq i \wedge$
$\text{partitioned}(a, 0, i, i+1, |a|-1) \wedge$
$\text{sorted}(a, i, |a|-1)$
$\text{partitioned}(a, 0, j-1, j, j)$ C_2

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                                 a[j] := a[j + 1];
                                 a[j + 1] := t};
}} return a}
```

Generate verification conditions and prove that they are valid

Predicates:

- $\text{sorted}(a, l, u)$: $\forall i, j (l \leq i \leq j \leq u \rightarrow a[i] \leq a[j])$
- $\text{partitioned}(a, l_1, u_1, l_2, u_2)$: $\forall i, j (l_1 \leq i \leq u_1 \leq l_2 \leq j \leq u_2 \rightarrow a[i] \leq a[j])$

Program Verification

$-1 \leq i < |a| \wedge$
$\text{partitioned}(a, 0, i, i+1, |a|-1) \wedge$
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$-1 \leq i < |a| \wedge 0 \leq j \leq i \wedge$
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Example: Does BUBBLESORT return a sorted array?

```
int [] BubbleSort(int[] a) {
    int i, j, t;
    for (i := |a| − 1; i > 0; i := i − 1) {
        for (j := 0; j < i; j := j + 1) {
            if (a[j] > a[j + 1]){t := a[j];
                                 a[j] := a[j + 1];
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}} return a}
```

Generate verification conditions and prove that they are valid

Predicates:

- $\text{sorted}(a, l, u)$: $\forall i, j (l \leq i \leq j \leq u \rightarrow a[i] \leq a[j])$
- $\text{partitioned}(a, l_1, u_1, l_2, u_2)$: $\forall i, j (l_1 \leq i \leq u_1 \leq l_2 \leq j \leq u_2 \rightarrow a[i] \leq a[j])$

To prove: $C_2(a) \wedge \text{Update}(a, a') \rightarrow C_2(a')$

Another Situation

Insertion of an element c in a sorted array a of length n

$$\begin{array}{l}\text{for } (i := 1; i \leq n; i := i + 1)\ \{\\ \qquad \text{if } a[i] \geq c\{n := n + 1\\ \qquad\qquad\qquad \text{for } (j := n; j > i; j := j - 1)\{a[i] := a[i - 1]\}\\ \qquad\qquad\qquad a[i] := c;\ \text{return } a\\ \}\}\ a[n + 1] := c;\ \text{return } a\end{array}$$

Task:

If the array was sorted before insertion it is sorted also after insertion.

$\text{Sorted}(a, n) \wedge \text{Update}(a, n, a', n') \wedge \neg\text{Sorted}(a', n') \models_{\mathcal{T}} \bot$?

Another Situation

Task:

If the array was sorted before insertion it is sorted also after insertion.

$\mathsf{Sorted}(a, n) \wedge \mathsf{Update}(a, n, a', n') \wedge \neg\mathsf{Sorted}(a', n') \models_{\mathcal{T}} \bot$?

$\mathsf{Sorted}(a, n)$	$\forall i, j(1 \leq i \leq j \leq n \rightarrow a[i] \leq a[j])$
$\mathsf{Update}(a, n, a', n')$	$\forall i((1 \leq i \leq n \wedge a[i] < c) \rightarrow a'[i] = a[i])$
	$\forall i((c \leq a(1) \rightarrow a'[1] := c)$
	$\forall i((a[n] < c \rightarrow a'[n+1] := c)$
	$\forall i((1 \leq i-1 \leq i \leq n \wedge a[i-1] < c \wedge a[i] \geq c) \rightarrow (a'[i] = c)$
	$\forall i((1 \leq i-1 \leq i \leq n \wedge a[i-1] \geq c \wedge a[i] \geq c \rightarrow a'[i] := a[i-1])$
	$n' := n+1$
$\neg\mathsf{Sorted}(a', n')$	$\exists k, l(1 \leq k \leq l \leq n' \wedge a[k] > a[l])$

Beyond the array property fragment

Extension: New arrays defined by case distinction – $\mathrm{Def}(f')$

$$\forall \overline{x}(\phi_i(\overline{x}) \rightarrow f'(\overline{x}) = s_i(\overline{x})) \qquad i \in I, \text{ where } \phi_i(\overline{x}) \wedge \phi_j(\overline{x}) \models_{\mathcal{T}_0} \bot \text{ for } i \neq j \quad (1)$$

$$\forall \overline{x}(\phi_i(\overline{x}) \rightarrow t_i(\overline{x}) \leq f'(\overline{x}) \leq s_i(\overline{x})) \qquad i \in I, \text{ where } \phi_i(\overline{x}) \wedge \phi_j(\overline{x}) \models_{\mathcal{T}_0} \bot \text{ for } i \neq j \quad (2)$$

where s_i, t_i are terms over the signature Σ such that $\mathcal{T}_0 \models \forall \overline{x}(\phi_i(\overline{x}) \rightarrow t_i(\overline{x}) \leq s_i(\overline{x}))$ for all $i \in I$.

$\mathcal{T}_0 \subseteq \mathcal{T}_0 \wedge \mathrm{Def}(f')$ has the property that for every set G of ground clauses in which there are no nested applications of f':

$$\mathcal{T}_0 \wedge \mathrm{Def}(f') \wedge G \models \bot \quad \text{iff} \quad \mathcal{T}_0 \wedge \mathrm{Def}(f')[G] \wedge G$$

(sufficient to use instances of axioms in $\mathrm{Def}(f')$ which are relevant for G)

- Some of the syntactic restrictions of the array property fragment can be lifted

Pointer Structures

[McPeak, Necula 2005]

- pointer sort p, scalar sort s; pointer fields (p $\rightarrow$ p); scalar fields (p $\rightarrow$ s);
- axioms: $\forall p \;\; \mathcal{E} \vee \mathcal{C}$;

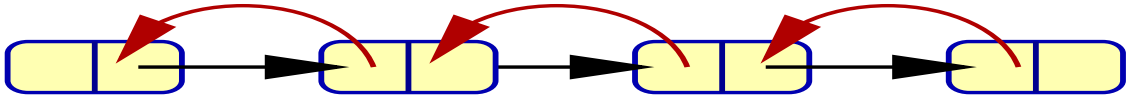
  $\mathcal{E}$ contains disjunctions of pointer equalities

  $\mathcal{C}$ contains scalar constraints

Assumption: If $f_1(f_2(\ldots f_n(p)))$ occurs in axiom, the axiom also contains:

$p{=}\text{null} \vee f_n(p){=}\text{null} \vee \cdots \vee f_2(\ldots f_n(p))){=}\text{null}$

Example: doubly-linked lists; ordered elements



$$\forall p\ (p \neq \text{null} \wedge p.\text{next} \neq \text{null} \rightarrow p.\text{next.prev} = p)$$
$$\forall p\ (p \neq \text{null} \wedge p.\text{prev} \neq \text{null} \rightarrow p.\text{prev.next} = p)$$
$$\forall p\ (p \neq \text{null} \wedge p.\text{next} \neq \text{null} \rightarrow p.\text{info} \leq p.\text{next.info})$$

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[McPeak, Necula 2005]

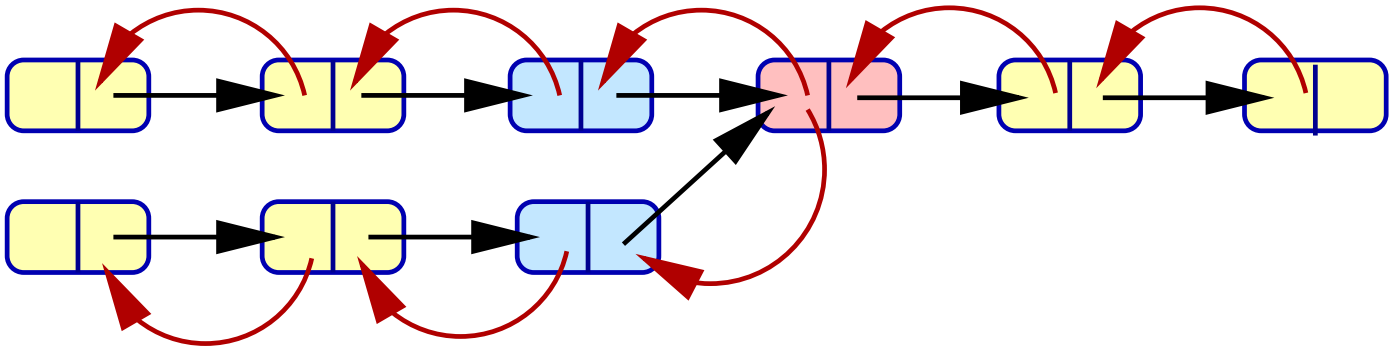
- pointer sort p, scalar sort s; pointer fields (p $\rightarrow$ p); scalar fields (p $\rightarrow$ s);
- axioms: $\forall p \;\; \mathcal{E} \vee \mathcal{C}$; $\mathcal{E}$ contains disjunctions of pointer equalities
  $\mathcal{C}$ contains scalar constraints

Assumption: If $f_1(f_2(\ldots f_n(p)))$ occurs in axiom, the axiom also contains:
$p{=}\text{null} \vee f_n(p){=}\text{null} \vee \cdots \vee f_2(\ldots f_n(p))){=}\text{null}$

Theorem. K set of clauses in the fragment above. Then for every set G of ground clauses, $(K \cup G) \cup \mathcal{T}_s \models \bot$ iff $K^{[G]} \cup \mathcal{T}_s \models \bot$

where $K^{[G]}$ is the set of instances of K in which the variables are replaced by subterms in G.

Example: A theory of doubly-linked lists

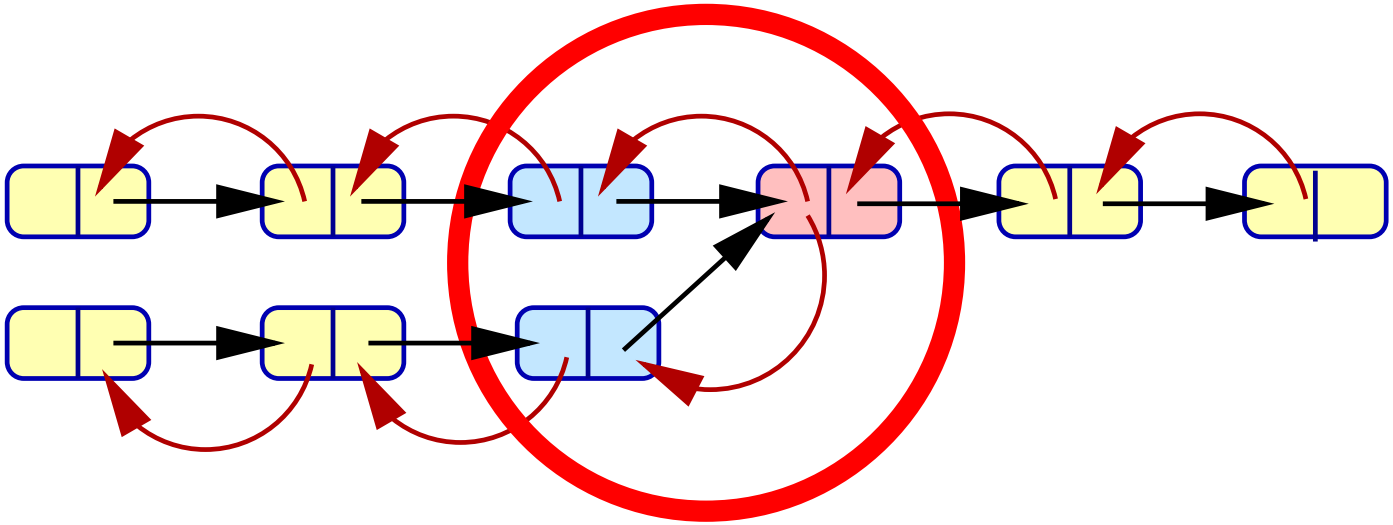


$$\forall p\ (p \neq \text{null} \wedge p.\text{next} \neq \text{null} \ \rightarrow \ p.\text{next.prev} = p)$$

$$\forall p\ (p \neq \text{null} \wedge p.\text{prev} \neq \text{null} \ \rightarrow \ p.\text{prev.next} = p)$$

$$\wedge \quad c{\neq}\text{null} \wedge c.\text{next}{\neq}\text{null} \wedge d{\neq}\text{null} \wedge d.\text{next}{\neq}\text{null} \wedge c.\text{next}{=}d.\text{next} \wedge c \neq d \quad \models \quad \bot$$

Example: A theory of doubly-linked lists

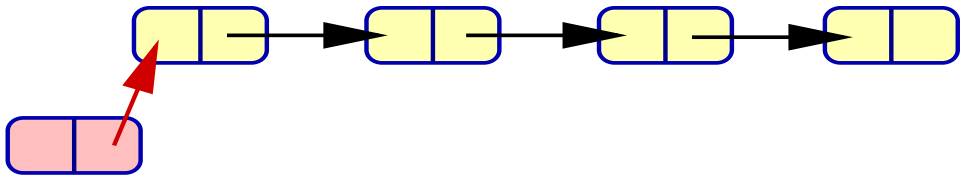


$(c \neq \text{null} \wedge c.\text{next} \neq \text{null} \rightarrow c.\text{next.prev} = c)$ $(c.\text{next} \neq \text{null} \wedge c.\text{next.next} \neq \text{null} \rightarrow c.\text{next.next.prev} = c.\text{next})$

$(d \neq \text{null} \wedge d.\text{next} \neq \text{null} \rightarrow d.\text{next.prev} = d)$ $(d.\text{next} \neq \text{null} \wedge d.\text{next.next} \neq \text{null} \rightarrow d.\text{next.next.prev} = d.\text{next})$

$$\wedge \quad c \neq \text{null} \wedge c.\text{next} \neq \text{null} \wedge d \neq \text{null} \wedge d.\text{next} \neq \text{null} \wedge c.\text{next} = d.\text{next} \wedge c \neq d \quad \models \quad \bot$$

Example: List insertion



Initially list is sorted: $p.\text{next} \neq \text{null} \rightarrow p.\text{prio} \geq p.\text{next.prio}$

$c.\text{prio} = x, c.\text{next} = \text{null}$

for all $p \neq c$ **do**

if $p.\text{prio} \leq x$ **then if** $\text{First}(p)$ **then** $c.\text{next}' = p$, $\text{First}'(c)$, $\neg\text{First}'(p)$ **endif**; $p.\text{next}' = p.\text{next}$

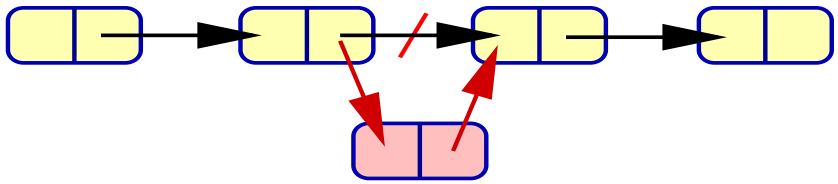
$p.\text{prio} > x$ **then** **case** $p.\text{next} = \text{null}$ **then** $p.\text{next}' := c, c.\text{next}' = \text{null}$

$p.\text{next} \neq \text{null} \wedge p.\text{next.prio} > x$ **then** $p.\text{next}' = p.\text{next}$

$p.\text{next} \neq \text{null} \wedge p.\text{next.prio} \leq x$ **then** $p.\text{next}' = c$, $c.\text{next}' = p.\text{next}$

Verification task: After insertion list remains sorted

Example: List insertion



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$p.\text{next} \neq \text{null} \wedge p.\text{next.prio} > x$ **then** $p.\text{next}' = p.\text{next}$

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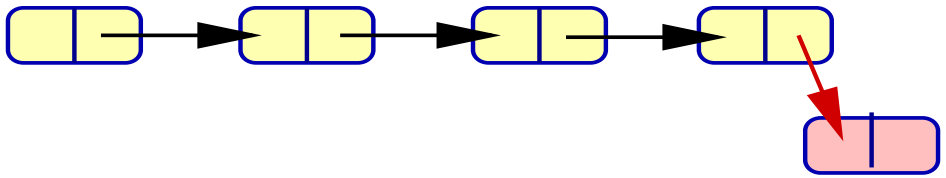
Verification task: After insertion list remains sorted

Example: List insertion



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for all $p \neq c$ **do**

if $p.\text{prio} \leq x$ **then if** $\text{First}(p)$ **then** $c.\text{next}' = p$, $\text{First}'(c)$, $\neg\text{First}'(p)$ **endif**; $p.\text{next}' = p.\text{next}$

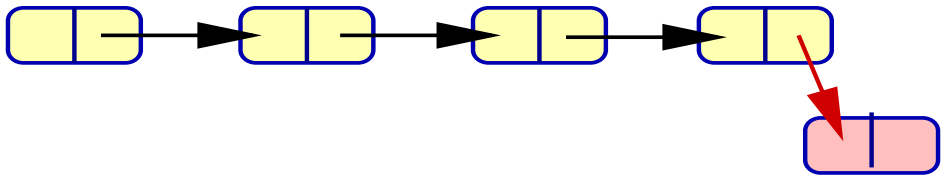
$p.\text{prio} > x$ **then** **case** $p.\text{next} = \text{null}$ **then** $p.\text{next}' := c, c.\text{next}' = \text{null}$

$p.\text{next} \neq \text{null} \wedge p.\text{next.prio} > x$ **then** $p.\text{next}' = p.\text{next}$

$p.\text{next} \neq \text{null} \wedge p.\text{next.prio} \leq x$ **then** $p.\text{next}' = c$, $c.\text{next}' = p.\text{next}$

Verification task: After insertion list remains sorted

Example: List insertion



Initially list is sorted: $\forall p(p.\text{next} \neq \text{null} \rightarrow p.\text{prio} \geq p.\text{next.prio})$

$\forall p(p{\neq}\text{null} \wedge p{\neq}c \wedge \text{prio}(p){\leq}x \wedge \text{First}(p) \rightarrow \text{next}'(c){=}p \wedge \text{First}'(c))$
$\forall p(p{\neq}\text{null} \wedge p{\neq}c \wedge \text{prio}(p){\leq}x \wedge \text{First}(p) \rightarrow \text{next}'(p){=}\text{next}(p) \wedge \neg\text{First}'(p))$

$\forall p(p{\neq}\text{null} \wedge p{\neq}c \wedge \text{prio}(p){\leq}x \wedge \neg\text{First}(p) \rightarrow \text{next}'(p){=}\text{next}(p))$

$\forall p(p{\neq}\text{null} \wedge p{\neq}c \wedge \text{prio}(p){>}x \wedge \text{next}(p){=}\text{null} \rightarrow \text{next}'(p){=}c$
$\forall p(p{\neq}\text{null} \wedge p{\neq}c \wedge \text{prio}(p){>}x \wedge \text{next}(p){=}\text{null} \rightarrow \text{next}'(c){=}\text{null})$

$\forall p(p{\neq}\text{null} \wedge p{\neq}c \wedge \text{prio}(p){>}x \wedge \text{next}(p){\neq}\text{null} \wedge \text{prio}(\text{next}(p)){>}x \rightarrow \text{next}'(p){=}\text{next}(p))$

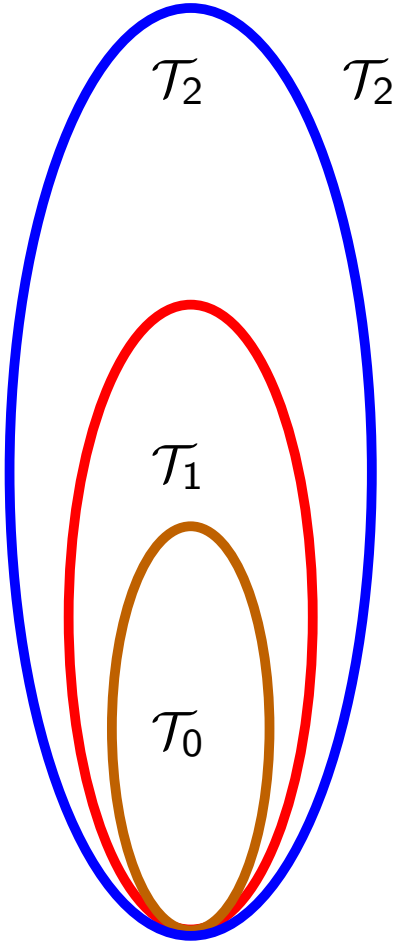
$\forall p(p{\neq}\text{null} \wedge p$ … $(p){=}c$
$\forall p(p{\neq}\text{null} \wedge p$ … $(c){=}\text{next}(p))$

We only need to use instances in which variables are replaced by ground subterms occurring in the problem

---

To check: $\text{Sorted}(\text{next}, \text{prio}) \wedge \text{Update}(\text{next}, \text{next}') \wedge p_0.\text{next}' {\neq} \text{null} \wedge p_0.\text{prio} \not\geq p_0.\text{next}'.\text{prio} \models \bot$

Example: List insertion



$\mathcal{T}_2 = \mathcal{T}_1 \cup \mathsf{Update}(\mathsf{next}, \mathsf{next}')$

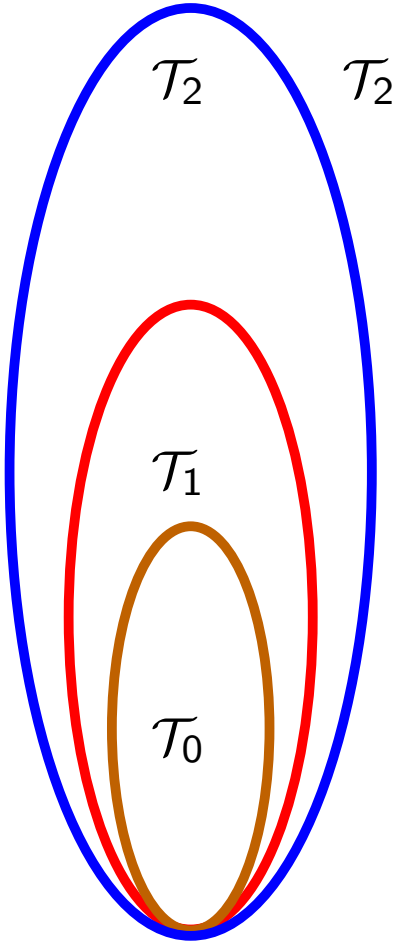
$\mathcal{T}_1 = \mathcal{T}_0 \cup \mathsf{Sorted}(\mathsf{next})$

$\mathcal{T}_0 = (\mathsf{Lists}, \mathsf{next})$

To show:

$$\mathcal{T}_2 \cup \underbrace{\neg\mathsf{Sorted}(\mathsf{next}')}_{G} \models \bot$$

Example: List insertion



$\mathcal{T}_2 = \mathcal{T}_1 \cup \boxed{\text{Update}(\text{next}, \text{next}')}$

Instantiate:

Hierarchical reasoning:

$\mathcal{T}_1 = \mathcal{T}_0 \cup \text{Sorted}(\text{next})$

$\mathcal{T}_0 = (\text{Lists}, \text{next})$

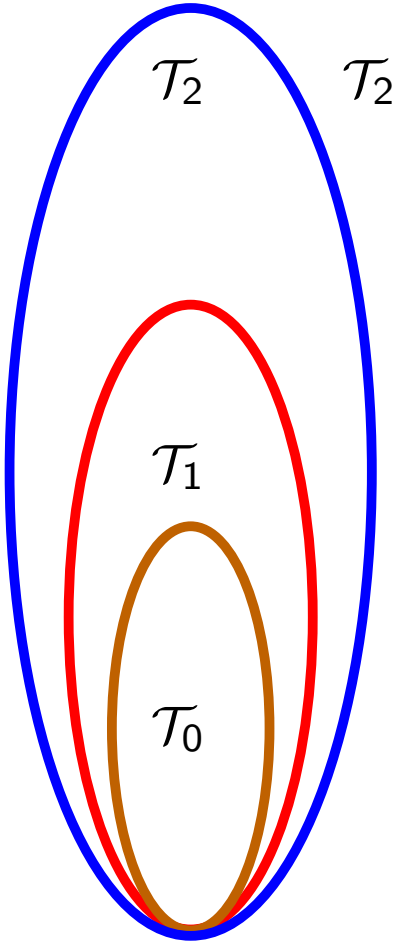
To show:

$\mathcal{T}_2 \cup \underbrace{\neg\text{Sorted}(\text{next}')}_{G} \models \bot$

$\mathcal{T}_1 \cup \underbrace{\boxed{\text{Update}(\text{next}, \text{next}')[G]} \cup G}_{G'} \models \bot$

$\mathcal{T}_1 \cup G'(\text{next}) \models \bot$

Example: List insertion



$\mathcal{T}_2 = \mathcal{T}_1 \cup \mathsf{Update}(\mathsf{next}, \mathsf{next}')$

$\mathcal{T}_1 = \mathcal{T}_0 \cup \mathsf{Sorted}(\mathsf{next})$

$\mathcal{T}_0 = (\mathsf{Lists}, \mathsf{next})$

To show:

$\mathcal{T}_2 \cup \underbrace{\neg\mathsf{Sorted}(\mathsf{next}')}_{G} \models \bot$

$\Downarrow$

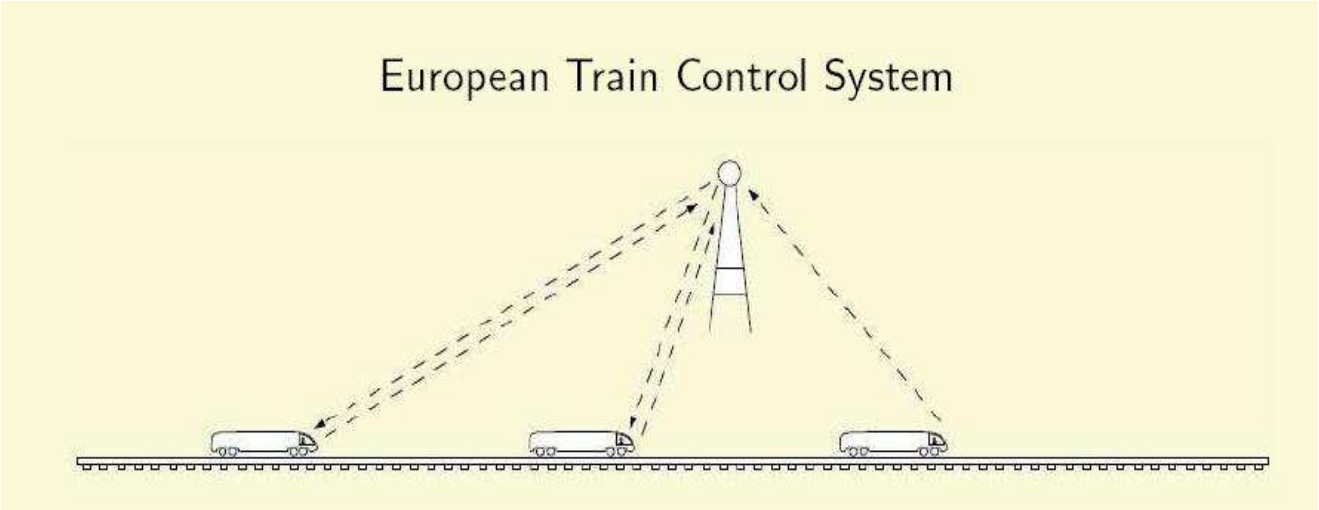
$\mathcal{T}_1 \cup G'(\mathsf{next}) \models \bot$

$\Downarrow$

$\mathcal{T}_0 \cup G'' \models \bot$

Example

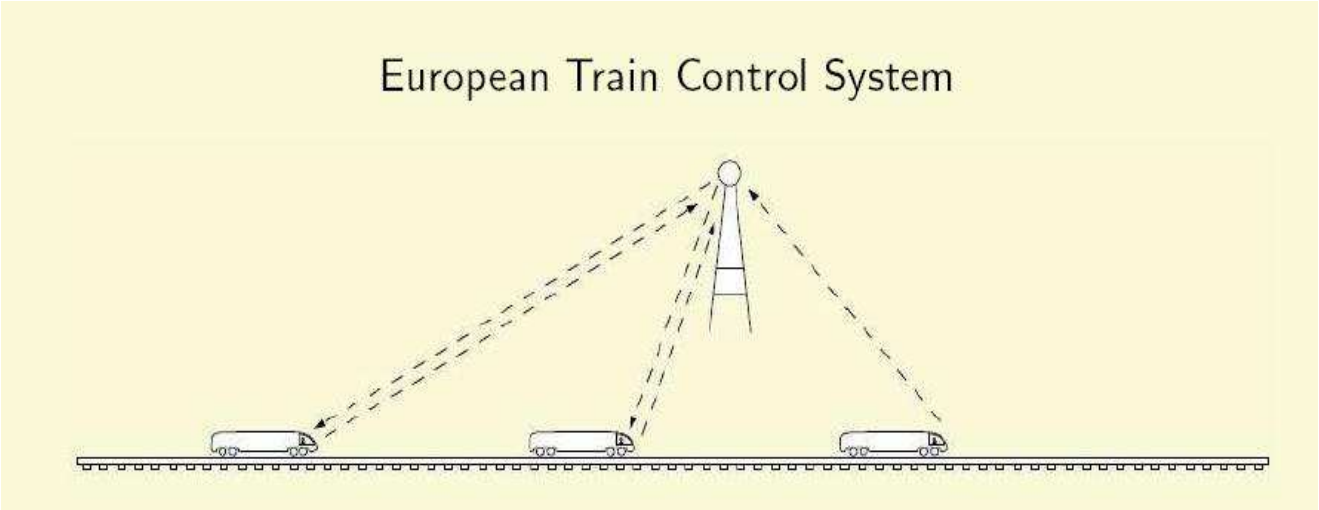
Simplified version of ETCS Case Study [Jacobs,VS'06, Faber,Jacobs,VS'07]



Number of trains:	$n \geq 0$	$\mathbb{Z}$
Minimum and maximum speed of trains:	$0 \leq \mathsf{min} < \mathsf{max}$	$\mathbb{R}$
Minimum secure distance:	$l_{\mathsf{alarm}} > 0$	$\mathbb{R}$
Time between updates:	$\Delta t > 0$	$\mathbb{R}$
Train positions before and after update:	$pos(i), pos'(i)$	$: \mathbb{Z} \to \mathbb{R}$

Example

Simplified version of ETCS Case Study [Jacobs,VS'06, Faber,Jacobs,VS'07]



Update(pos, pos′) :

- $\forall i\ (i = 0 \rightarrow pos(i) + \Delta t{*}\mathsf{min} \leq pos'(i) \leq pos(i) + \Delta t{*}\mathsf{max})$
- $\forall i\ (0 < i < n\ \wedge\ pos(i-1) > 0\ \wedge\ pos(i-1) - pos(i) \geq l_{\mathsf{alarm}}$
  $\rightarrow pos(i) + \Delta t * \mathsf{min} \leq pos'(i) \leq pos(i) + \Delta t{*}\mathsf{max})$

...

Example

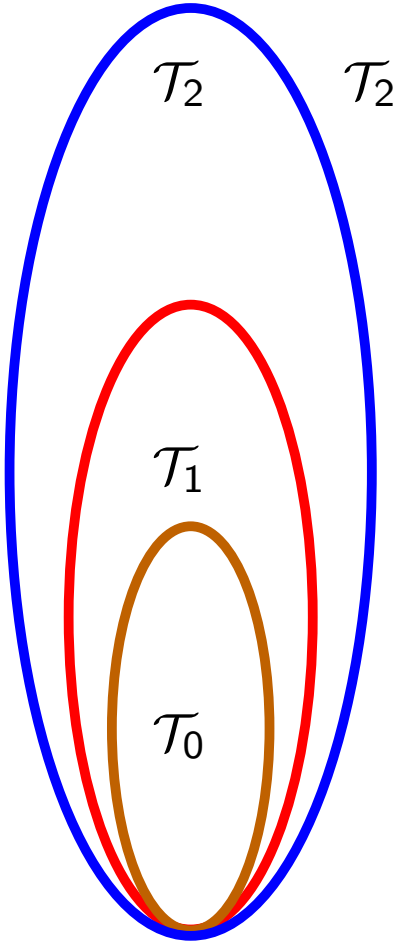
Safety property: No collisions $\quad \mathsf{Safe}(\mathsf{pos}) : \quad \forall i, j (i < j \rightarrow \mathsf{pos}(i) > \mathsf{pos}(j))$

Inductive invariant: $\mathsf{Safe}(\mathsf{pos}) \wedge \mathsf{Update}(\mathsf{pos}, \mathsf{pos}') \wedge \neg \mathsf{Safe}(\mathsf{pos}') \models_{\mathcal{T}_S} \bot$

where $\mathcal{T}_S$ is the extension of the (disjoint) combination $\mathbb{R} \cup \mathbb{Z}$
with two functions, $\mathsf{pos}, \mathsf{pos}' : \mathbb{Z} \rightarrow \mathbb{R}$

Our idea: Use chains of "instantiation" + reduction.

Example



$\mathcal{T}_2 = \mathcal{T}_1 \cup \mathsf{Update}(\mathsf{pos}, \mathsf{pos}')$

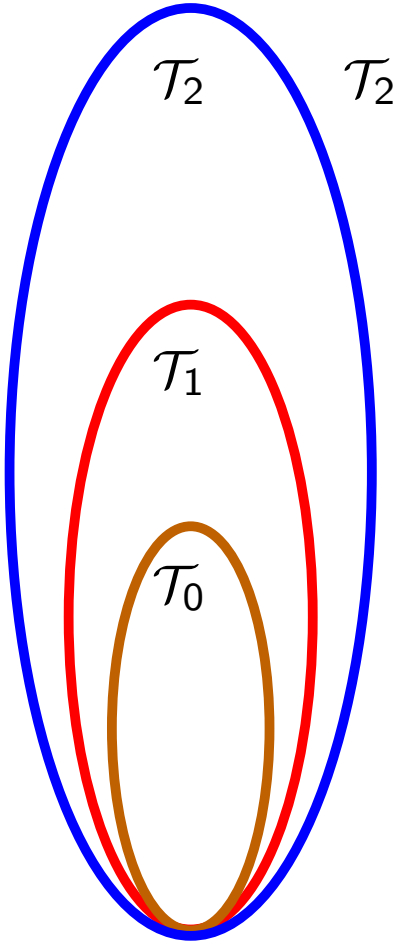
$\mathcal{T}_1 = \mathcal{T}_0 \cup \mathsf{Safe}(\mathsf{pos})$

$\mathcal{T}_0 = \mathbb{R} \cup \mathbb{Z}$

To show:

$\mathcal{T}_2 \cup \underbrace{\neg\mathsf{Safe}(\mathsf{pos}')}_{G} \models \bot$

Example



$\mathcal{T}_2 = \mathcal{T}_1 \cup \text{Update}(\text{pos}, \text{pos}')$

$\mathcal{T}_1 = \mathcal{T}_0 \cup \text{Safe}(\text{pos})$

$\mathcal{T}_0 = \mathbb{R} \cup \mathbb{Z}$

To show:

$\mathcal{T}_2 \cup \underbrace{\neg\text{Safe}(\text{pos}')}_{G} \models \bot$

$\Downarrow$

$\mathcal{T}_1 \cup G'(\text{pos}) \models \bot$

$\Downarrow$

$\mathcal{T}_0 \cup G'' \models \bot$

$\Phi(c, \overline{c}_{\text{pos}'}, \overline{d}_{\text{pos}}, n, l_{\text{alarm}}, \text{min}, \text{max}, \Delta t) \models \bot$

Method 1: SAT checking/ Counterexample generation

Method 2: Quantifier elimination

relationships between parameters which guarantee safety

More complex ETCS Case studies

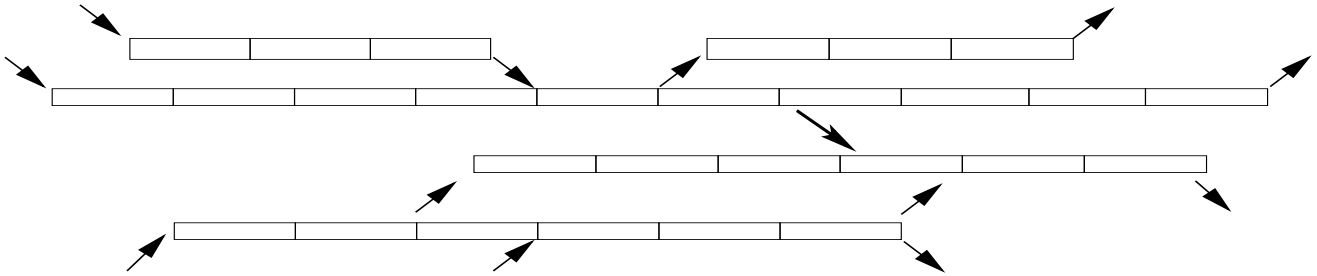
[Faber, Jacobs, VS, 2007]

- Take into account also:
  - Emergency messages
  - Durations
- Specification language: CSP-OZ-DC
  - Reduction to satisfiability in theories for which decision procedures exist
- **Tool chain:** [Faber, Ihlemann, Jacobs, VS]

CSP-OZ-DC $\mapsto$ Transition constr. $\mapsto$ Decision procedures (H-PILoT)

Example 2: Parametric topology

- **Complex track topologies** [Faber, Ihlemann, Jacobs, VS, ongoing work]

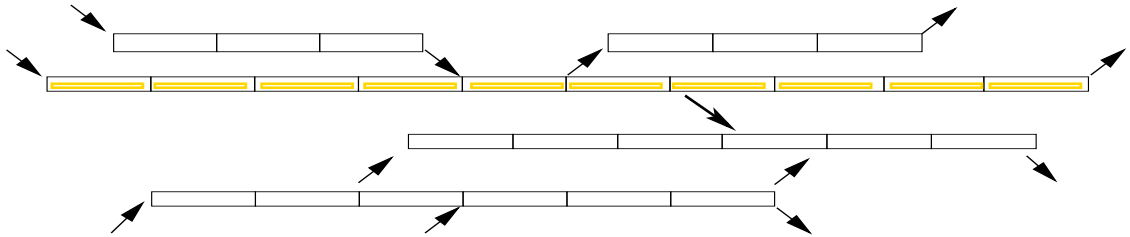


Assumptions:

- No cycles
- in-degree (out-degree) of associated graph at most 2.

Parametricity and modularity

- **Complex track topologies** [Faber, Ihlemann, Jacobs, VS, ongoing work]



Assumptions:

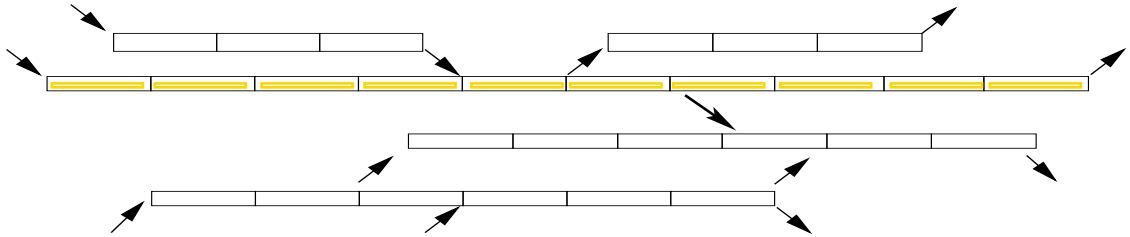
- No cycles
- in-degree (out-degree) of associated graph at most 2.

Approach:

- Decompose the system in trajectories (linear rail tracks; may overlap)
- Task 1: - Prove safety for trajectories with incoming/outgoing trains
  - Conclude that for control rules in which trains have sufficient freedom (and if trains are assigned unique priorities) safety of all trajectories implies safety of the whole system
- Task 2: - General constraints on parameters which guarantee safety

Parametricity and modularity

- **Complex track topologies** [Faber, Ihlemann, Jacobs, VS, ongoing work]



Assumptions:

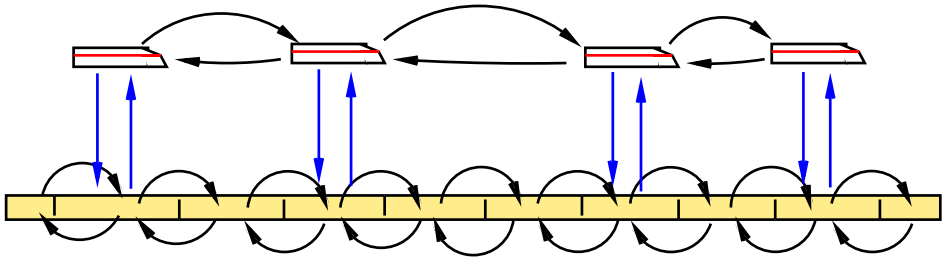
- No cycles
- in-degree (out-degree) of associated graph at most 2.

Data structures:

- 2-sorted pointers

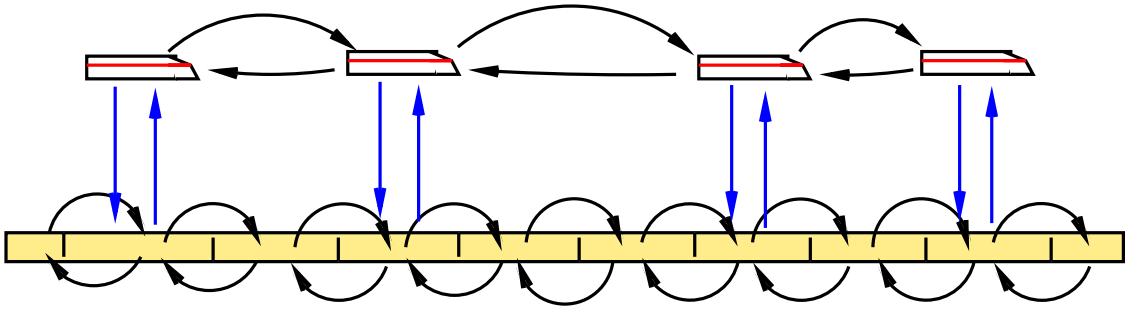
p_1: trains

p_2: segments



- scalar fields ($f{:}p_i \to \mathbb{R}$, $g{:}p_i \to \mathbb{Z}$)
- updates efficient decision procedures (H-PiLoT)

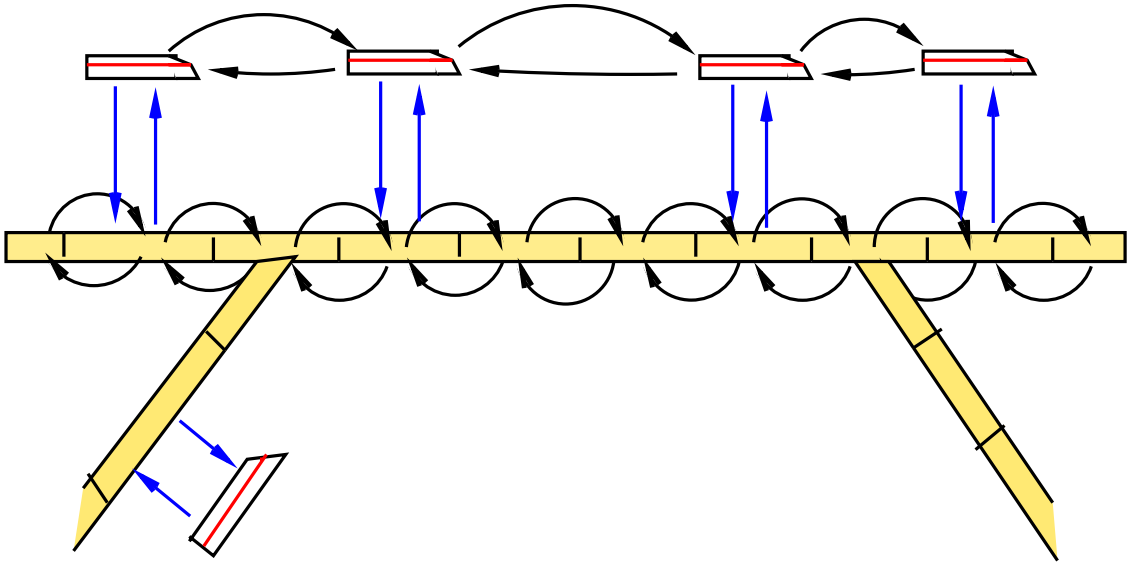
Incoming and outgoing trains



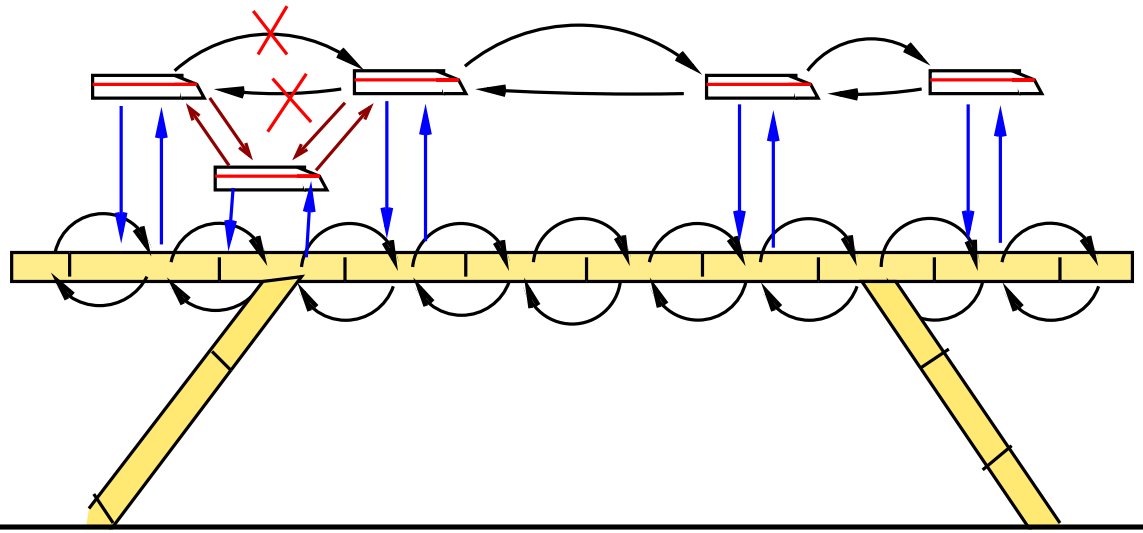
Example 1: Speed Update

$$\begin{aligned}
&\mathrm{pos}(t) < \mathrm{length}(\mathrm{segm}(t)) - d \;\rightarrow\; 0 \leq \mathrm{spd}'(t) \leq \mathrm{lmax}(\mathrm{segm}(t)) \\
&\mathrm{pos}(t) \geq \mathrm{length}(\mathrm{segm}(t)) - d \;\wedge\; \mathrm{alloc}(\mathrm{next}_s(\mathrm{segm}(t))) = \mathrm{tid}(t) \\
&\qquad\qquad \rightarrow\; 0 \leq \mathrm{spd}'(t) \leq \min(\mathrm{lmax}(\mathrm{segm}(t)), \mathrm{lmax}(\mathrm{next}_s(\mathrm{segm}(t)))) \\
&\mathrm{pos}(t) \geq \mathrm{length}(\mathrm{segm}(t)) - d \;\wedge\; \mathrm{alloc}(\mathrm{next}_s(\mathrm{segm}(t))) \neq \mathrm{tid}(t) \\
&\qquad\qquad \rightarrow\; \mathrm{spd}'(t) = \max(\mathrm{spd}(t) - \mathrm{decmax}, 0)
\end{aligned}$$

Incoming and outgoing trains



Incoming and outgoing trains



Example 2: Enter Update (also updates for segm', spd', pos', train')

Assume: $s_1 \neq \text{null}_s$, $t_1 \neq \text{null}_t$, $\text{train}(s) \neq t_1$, $\text{alloc}(s_1) = \text{idt}(t_1)$

$t{\neq}t_1, \text{ids}(\text{segm}(t)){<}\text{ids}(s_1), \text{next}_t(t){=}\text{null}_t, \text{alloc}(s_1){=}\text{tid}(t_1) \rightarrow \text{next}'(t){=}t_1 \wedge \text{next}'(t_1){=}\text{null}_t$

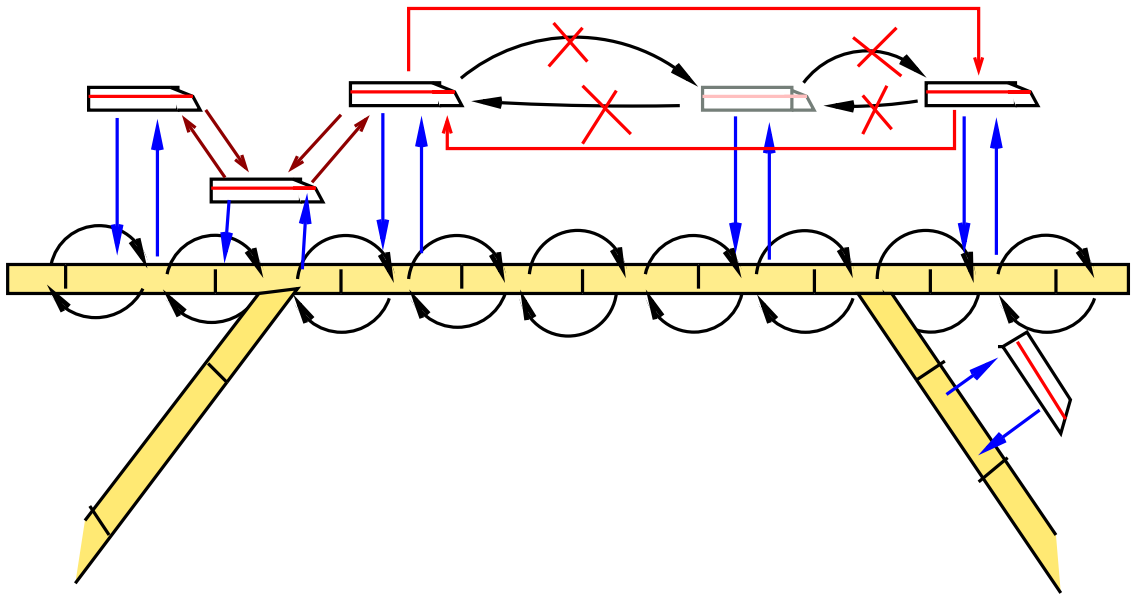
$t{\neq}t_1, \text{ids}(\text{segm}(t)){<}\text{ids}(s_1), \text{alloc}(s_1){=}\text{tid}(t_1), \text{next}_t(t){\neq}\text{null}_t, \text{ids}(\text{segm}(\text{next}_t(t))){\leq}\text{ids}(s_1)$

$\rightarrow \text{next}'(t){=}\text{next}_t(t)$

...

$t{\neq}t_1, \text{ids}(\text{segm}(t)){\geq}\text{ids}(s_1) \rightarrow \text{next}'(t){=}\text{next}_t(t)$

Incoming and outgoing trains



Safety property

Safety property we want to prove: no two trains ever occupy the same track segment:

$$(\text{Safe}) := \forall t_1, t_2 \;\; \text{segm}(t_1) = \text{segm}(t2) \rightarrow t_1 = t_2$$

In order to prove that (Safe) is an invariant of the system, we need to find a suitable invariant (Inv(i)) for every control location i of the TCS, and prove:

$$(\text{Inv}(i)) \models (\text{Safe}) \text{ for all locations } i$$

and that the invariants are preserved under all transitions of the system,

$$(\text{Inv}(i)) \wedge (\text{Update}) \models (\text{Inv}'(j))$$

whenever (Update) is a transition from location i to j .

Safety property

Need additional invariants.

- generate by hand [Faber, Ihlemann, Jacobs, VS, ongoing]

  use the capabilities of H-PILoT of generating counterexamples

- generate automatically [VS, work in progress]

Ground satisfiability problems for pointer data structures

the decision procedures presented before can be used without problems

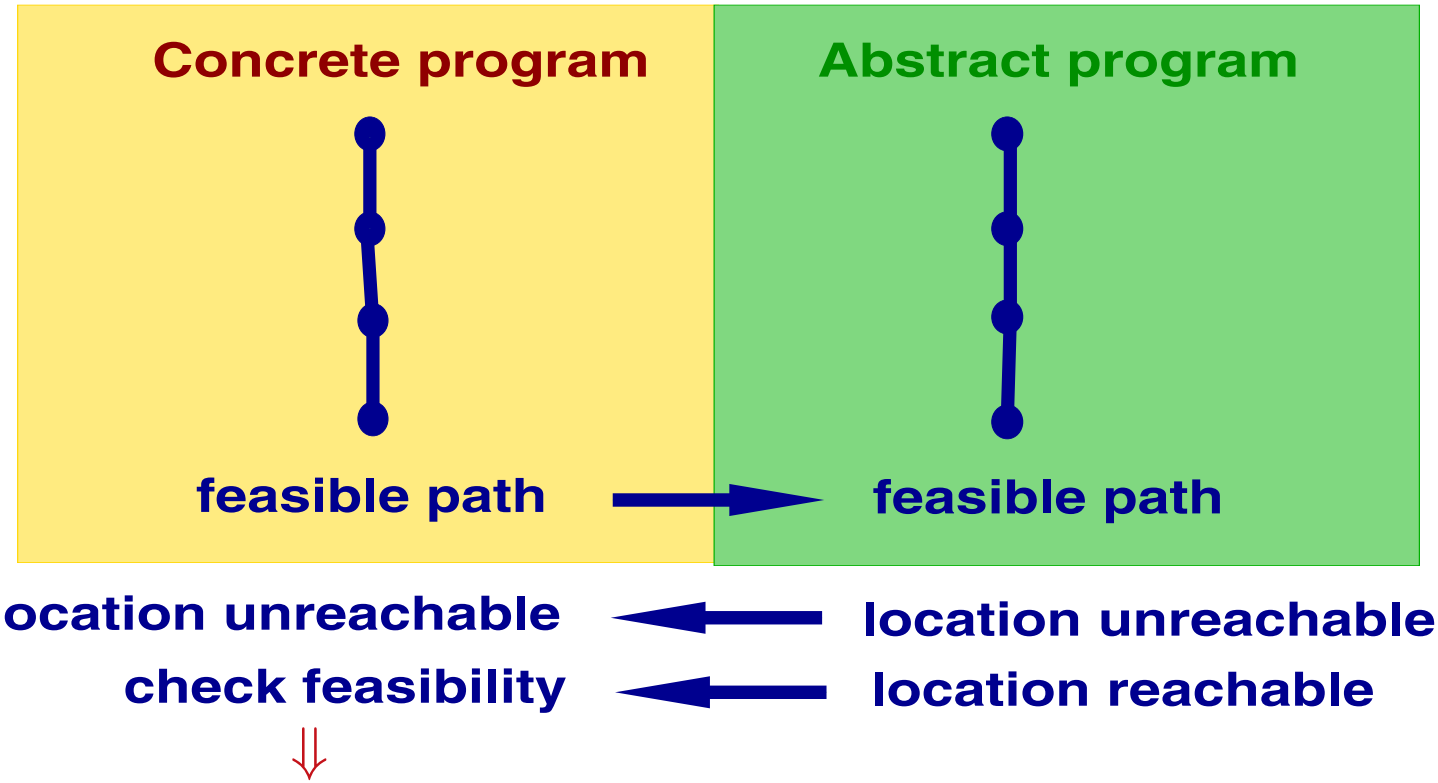
Other interesting topics

- Generate invariants

Other interesting topics

- Generate invariants
- Verification by abstraction/refinement

Abstraction-based Verification



conjunction of constraints: $\phi(1) \wedge Tr(1,2) \wedge \cdots \wedge Tr(n-1,n) \wedge \neg \mathsf{safe}(n)$

- satisfiable: feasible path
- unsatisfiable: refine abstract program s.t. the path is not feasible

[McMillan 2003-2006] use 'local causes of inconsistency'

$\mapsto$ compute interpolants

Follow-up

- Seminar on Decision Procedures and Applications (SS 2013)

- Lecture "Formal Specification and Verification" (SS 2013)

- Forschungs Praktika in the area of decision procedures and applications

- BSc Theses and MSc Theses in the area of decision procedures for verification