Decision Procedures for Verification

Combinations of decision procedures (4)

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Until Now

• Decision procedures for specific theories

in some cases for satisfiability of ground formulae only

• Combinations of decision procedures

Nelson/Oppen (for conjunctions of ground literals)

• DPLL(T)

for conjunctions of ground clauses

• Formulae with quantifiers

a theory of arrays (started last time)

A theory of arrays

We consider the theory of arrays in a many-sorted setting.

Syntax:

- Sorts: Elem (elements), Array (arrays) and Index (indices, here integers).
- Function symbols: read, write.

 $a(read) = Array \times Index \rightarrow Element$

 $a(write) = Array \times Index \times Element \rightarrow Array$

Theories of arrays

We consider the theory of arrays in a many-sorted setting.

Theory of arrays \mathcal{T}_{arrays} :

- \mathcal{T}_i (theory of indices): Presburger arithmetic
- \mathcal{T}_e (theory of elements): arbitrary
- Axioms for read, write

$$read(write(a, i, e), i) \approx e$$

 $j \not\approx i \lor read(write(a, i, e), j) = read(a, j).$

Theories of arrays

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Theory of arrays T_{arrays} :

- T_i (theory of indices): Presburger arithmetic
- \mathcal{T}_e (theory of elements): arbitrary
- Axioms for read, write

$$read(write(a, i, e), i) \approx e$$

 $j \not\approx i \lor read(write(a, i, e), j) = read(a, j).$

Fact: Undecidable in general.

Goal: Identify a fragment of the theory of arrays which is decidable.

A decidable fragment

Index guard a positive Boolean combination of atoms of the form
 t ≤ u or t = u where t and u are either a variable or a ground term of sort Index

Example: $(x \le 3 \lor x \approx y) \land y \le z$ is an index guard Example: $x + 1 \le c$, $x + 3 \le y$, $x + x \le 2$ are not index guards.

• Array property formula [Bradley, Manna, Sipma'06]

 $(\forall i)(\varphi_I(i) \rightarrow \varphi_V(i))$, where:

 φ_I : index guard

 φ_V : formula in which any universally quantified *i* occurs in a direct array read; no nestings

Example: $c \le x \le y \le d \rightarrow a(x) \le a(y)$ is an array property formula Example: $x < y \rightarrow a(x) < a(y)$ is not an array property formula

Decision Procedure

(Rules should be read from top to bottom)

Step 1: Put F in NNF.

Step 2: Apply the following rule exhaustively to remove writes:

$$\frac{F[\textit{write}(a, i, v)]}{F[a'] \land a'[i] = v \land (\forall j.j \neq i \rightarrow a[j] = a'[j])} \quad \text{for fresh } a' \text{ (write)}$$

Given a formula F containing an occurrence of a write term write(a, i, v), we can substitute every occurrence of write(a, i, v) with a fresh variable a'and explain the relationship between a' and a. **Step 3** Apply the following rule exhaustively to remove existential quantification:

$$\frac{F[\exists i.G[i]]}{F[G[j]]}$$
 for fresh j (exists)

Existential quantification can arise during Step 1 if the given formula contains a negated array property.

Steps 4-6 accomplish the reduction of universal quantification to finite conjunction.

The main idea is to select a set of symbolic index terms on which to instantiate all universal quantifiers.

Step 4 From the output F3 of Step 3, construct the index set \mathcal{I} :

 $\mathcal{I} = \{\lambda\} \cup \\ \{t \mid \cdot[t] \in F3 \text{ such that } t \text{ is not a universally quantified variable}\} \cup \\ \{t \mid t \text{ occurs as an } evar \text{ in the parsing of index guards}\}$

(evar is any constant, ground term, or unquantified variable.)

This index set is the finite set of indices that need to be examined. It includes all terms t that occur in some read(a, t) anywhere in F (unless it is a universally quantified variable) and all terms t that are compared to a universally quantified variable in some index guard.

 λ is a fresh constant that represents all other index positions that are not explicitly in $\mathcal{I}.$

Theories of arrays

Step 5 Apply the following rule exhaustively to remove universal quantification:

$$\frac{H[\forall \overline{i}.F[i] \to G[i]]}{H\left[\bigwedge_{\overline{i}\in\mathcal{I}^n}(F[\overline{i}] \to G[\overline{i}])\right]} \quad \text{(forall)}$$

where *n* is the size of the list of quantified variables \overline{i} .

This is the key step.

It replaces universal quantification with finite conjunction over the index set. The notation $\overline{i} \in \mathcal{I}^n$ means that the variables \overline{i} range over all *n*-tuples of terms in \mathcal{I} .

Theories of arrays

Step 6: From the output *F*5 of Step 5, construct

$$F6: \qquad F5 \land \bigwedge_{i \in \mathcal{I} \setminus \{\lambda\}} \lambda \neq i$$

The new conjuncts assert that the variable λ introduced in Step 4 is unique: it does not equal any other index mentioned in F5.

Step 7: Decide the TA-satisfiability of *F*6 using the decision procedure for the quantifier free fragment.

Consider the array property formula

 $F: write(a, l, v)[k] = b[k] \land b[k] \neq v \land a[k] = v \land (\forall i.i \neq l \rightarrow a[i] = b[i])$

It contains one array property,

$$\forall i.i \neq l \rightarrow a[i] = b[i]$$

index guard: $i \neq l := (i \leq l - 1 \lor i \geq l + 1)$ value constraint: a[i] = b[i]

Step 1: The formula is already in NNF.

Step 2: We rewrite F as:

F2:
$$a'[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\forall i.i \neq l \rightarrow a[i] = b[i])$$

 $\wedge a'[l] = v \wedge (\forall j.j \neq l \rightarrow a[j] = a'[j]).$

Consider the array property formula

 $F: write(a, l, v)[k] = b[k] \land b[k] \neq v \land a[k] = v \land (\forall i.i \neq l \rightarrow a[i] = b[i])$

Step 2: We rewrite F as:

$$F2: \quad a'[k] = b[k] \land b[k] \neq v \land a[k] = v \land (\forall i.i \neq l \rightarrow a[i] = b[i]) \\ \land a'[l] = v \land (\forall j.j \neq l \rightarrow a[j] = a'[j]).$$

index guards:
$$i \neq l := (i \leq l - 1 \lor i \geq l + 1)$$
 value constraint: $a[i] = b[i]$
 $i \neq l := (j \leq l - 1 \lor j \geq l + 1)$ value constraint: $a[i] = a'[j]$

Step 3: F2 does not contain any existential quantifiers \mapsto F3 = F2. Step 4: The index set is

$$\mathcal{I} = \{\lambda\} \cup \{k\} \cup \{\textit{I},\textit{I}-1,\textit{I}+1\} = \{\lambda,\textit{k},\textit{I},\textit{I}-1,\textit{I}+1\}$$

Consider the array property formula

 $F: write(a, l, v)[k] = b[k] \land b[k] \neq v \land a[k] = v \land (\forall i.i \neq l \rightarrow a[i] = b[i])$ Step 3:

F3:
$$a'[k] = b[k] \land b[k] \neq v \land a[k] = v \land (\forall i.i \neq l \rightarrow a[i] = b[i])$$

 $\land a'[l] = v \land (\forall j.j \neq l \rightarrow a[j] = a'[j]).$

Step 4: $I = \{\lambda, k, l, l - 1, l + 1\}$

Step 5: we replace universal quantification as follows:

$$F5: \quad a'[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge \bigwedge_{i \in \mathcal{I}} (i \neq l \to a[i] = b[i])$$
$$\wedge a'[l] = v \wedge \bigwedge_{i \in \mathcal{I}} (j \neq l \to a[j] = a'[j]).$$

Consider the array property formula

$$F: write(a, l, v)[k] = b[k] \land b[k] \neq v \land a[k] = v \land (\forall i.i \neq l \rightarrow a[i] = b[i])$$
$$\mathcal{I} = \{\lambda, k, l, l - 1, l + 1\}$$

Step 5 (continued) Expanding produces:

$$F5': a'[k] = b[k] \land b[k] \neq v \land a[k] = v \land$$

$$(\lambda \neq l \rightarrow a[\lambda] = b[\lambda]) \land (k \neq l \rightarrow a[k] = b[k]) \land (l \neq l \rightarrow a[l] = b[l]) \land$$

$$(l - 1 \neq l \rightarrow a[l - 1] = b[l - 1]) \land (l + 1 \neq l \rightarrow a[l + 1] = b[l + 1]) \land$$

$$a'[l] = v \land (\lambda \neq l \rightarrow a[\lambda] = a'[\lambda]) \land (k \neq l \rightarrow a[k] = a'[k]) \land$$

$$(l \neq l \rightarrow a[l] = a'[l]) \land (l - 1 \neq l \rightarrow a[l - 1] = a'[l - 1]) \land$$

$$(l + 1 \neq l \rightarrow a[l + 1] = a'[l + 1]).$$

Consider the array property formula

 $F: write(a, l, v)[k] = b[k] \land b[k] \neq v \land a[k] = v \land (\forall i.i \neq l \rightarrow a[i] = b[i])$

$$\mathcal{I} = \{\lambda\} \cup \{k\} \cup \{I\} = \{\lambda, k, I\}$$

Step 5 (continued): Simplifying produces

$$F''5: \quad a'[k] = b[k] \wedge b[k] \neq v \wedge a[k] = v \wedge (\lambda \neq l \rightarrow a[\lambda] = b[\lambda])$$

$$\wedge (k \neq l \rightarrow a[k] = b[k]) \wedge a[l-1] = b[l-1] \wedge a[l+1] = b[l+1]$$

$$\wedge a'[l] = v \wedge (\lambda \neq l \rightarrow a[\lambda] = a'[\lambda])$$

$$\wedge (k \neq l \rightarrow a[k] = a'[k]) \wedge a[l-1] = a'[l-1] \wedge a[l+1] = a'[l+1]$$

Consider the array property formula

$$F: write(a, l, v)[k] = b[k] \land b[k] \neq v \land a[k] = v \land (\forall i.i \neq l \rightarrow a[i] = b[i])$$

Step 6 distinguishes λ from other members of I:

$$F6: a'[k] = b[k] \land b[k] \neq v \land a[k] = v \land (\lambda \neq l \rightarrow a[\lambda] = b[\lambda])$$

$$\land (k \neq l \rightarrow a[k] = b[k]) \land a[l-1] = b[l-1] \land a[l+1] = b[l+1]$$

$$\land a'[l] = v \land (\lambda \neq l \rightarrow a[\lambda] = a'[\lambda])$$

$$\land (k \neq l \rightarrow a[k] = a'[k]) \land a[l-1] = a'[l-1] \land a[l+1] = a'[l+1]$$

$$\land \lambda \neq k \land \lambda \neq l \land \lambda \neq l-1 \land \lambda \neq l+1.$$

Consider the array property formula

$$F: write(a, l, v)[k] = b[k] \land b[k] \neq v \land a[k] = v \land (\forall i.i \neq l \rightarrow a[i] = b[i])$$

Step 6 Simplifying, we have

$$F'6: a'[k] = b[k] \land b[k] \neq v \land a[k] = v \land a[\lambda] = b[\lambda]$$

$$\land a[k] = b[k] \land a[l-1] = b[l-1] \land a[l+1] = b[l+1]$$

$$\land a'[l] = v \land a[\lambda] = a'[\lambda]$$

$$\land (k \neq l \rightarrow a[k] = a'[k]) \land a[l-1] = a'[l-1] \land a[l+1] = a'[l+1]$$

$$\land \lambda \neq k \land \lambda \neq l \land \lambda \neq l-1 \land \lambda \neq l+1.$$

We can use for instance DPLL(T). Alternative: Case distinction. There are two cases to consider.

(1) If
$$k=l$$
, then $a'[l]=v$ and $a'[k]=b[k]$ imply $b[k]=v$, yet $b[k]\neq v$.

(2) If $k \neq l$, then a[k] = v and a[k] = b[k] imply b[k] = v, but again $b[k] \neq v$.

Hence, F'6 is TA-unsatisfiable, indicating that F is TA-unsatisfiable.

Consider a formula F from the array property fragment . The output F6 of Step 6 is T_{arrays} -equisatisfiable to F.

Proof (Soundness) Step 1-6 preserve satisfiability (Fi is a logical consequence of Fi-1).

Consider a formula F from the array property fragment . The output F6 of Step 6 is T_{arrays} -equisatisfiable to F.

Proof (Completeness)

Step 6: From the output *F*5 of Step 5, construct

$$F6: F5 \land \bigwedge_{i \in \mathcal{I} \setminus \{\lambda\}} \lambda \neq i$$

Assume that F6 is satisfiabile. Clearly F5 has a model.

Consider a formula F from the array property fragment . The output F6 of Step 6 is T_{arrays} -equisatisfiable to F.

Proof (Completeness)

Step 5 Apply the following rule exhaustively to remove universal quantification:

$$\frac{H[\forall \overline{i}.F[i] \to G[i]]}{H\left[\bigwedge_{\overline{i} \in \mathcal{I}^n} (F[\overline{i}] \to G[\overline{i}])\right]} \quad \text{(forall)}$$

Assume that F5 is satisfiabile. Let $\mathcal{A} = (\mathbb{Z}, \text{Elem}, \{a_A\}_{a \in Arrays}, ...)$ be a model for F5. Construct a model \mathcal{B} for F4 as follows.

For $x \in \mathbb{Z}$: I(x) (u(x)) closest left (right) neighbor of x in \mathcal{I} .

$$a_{\mathcal{B}}(x) = \begin{cases} a_{\mathcal{A}}(l(x)) & \text{if } x - l(x) \le u(x) - x \text{ or } u(x) = \infty \\ a_{\mathcal{A}}(u(x)) & \text{if } x - l(x) > u(x) - x \text{ or } l(x) = -\infty \end{cases}$$

Consider a formula F from the array property fragment . The output F6 of Step 6 is T_{arrays} -equisatisfiable to F.

Proof (Completeness)

Step 3 Apply the following rule exhaustively to remove existential quantification:

$$\frac{F[\exists i.G[i]]}{F[G[j]]}$$
 for fresh j (exists)

If F3 has model then F2 has model

Consider a formula F from the array property fragment . The output F6 of Step 6 is T_{arrays} -equisatisfiable to F.

Proof (Completeness)

Step 2: Apply the following rule exhaustively to remove writes:

$$\frac{F[write(a, i, v)]}{F[a'] \land a'[i] = v \land (\forall j.j \neq i \rightarrow a[j] = a'[j])} \quad \text{for fresh } a' \text{ (write)}$$

Given a formula F containing an occurrence of a write term write(a, i, v), we can substitute every occurrence of write(a, i, v) with a fresh variable a' and explan the relationship between a' and a.

If F2 has a model then F1 has a model.

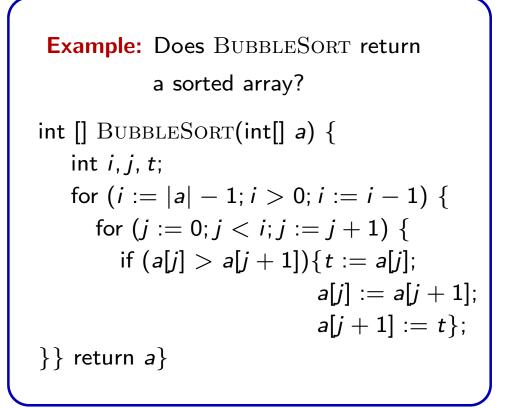
Step 1: Put F in NNF: NNF F1 is equivalent to F.

Theorem (Complexity) Suppose $(T_{index} \cup T_{elem})$ -satisfiability is in NP. For sub-fragments of the array property fragment in which formulae have bounded-size blocks of quantifiers, T_{arrays} -satisfiability is NP-complete.

Proof NP-hardness is clear.

That the problem is in NP follows easily from the procedure: instantiating a block of n universal quantifiers quantifying subformula G over index set Iproduces $|I| \cdot n$ new subformulae, each of length polynomial in the length of G. Hence, the output of Step 6 is of length only a polynomial factor greater than the input to the procedure for fixed n.

Program verification



Program Verification

 $-1 \leq i < |a| \land 0 \leq j \leq i \land$ partitioned(a, 0, i, i + 1, |a| - 1) \land sorted(a, i, |a| - 1) partitioned(a, 0, j - 1, j, j) C₂ a sorted array? int [] BUBBLESORT(int[] a) { int i, j, t; for (i := |a| - 1; i > 0; i := i - 1) { for (j := 0; j < i; j := j + 1) { if (a[j] > a[j + 1]){t := a[j]; a[j] := a[j + 1]; a[j + 1] := t}; }} return a}

Example: Does BUBBLESORT return

Generate verification conditions and prove that they are valid Predicates:

- sorted(a, l, u): $\forall i, j(l \le i \le j \le u \rightarrow a[i] \le a[j])$
- partitioned(a, l_1 , u_1 , l_2 , u_2): $\forall i, j(l_1 \leq i \leq u_1 \leq l_2 \leq j \leq u_2 \rightarrow a[i] \leq a[j])$

Program Verification

 $-1 \leq i < |a| \land$ partitioned(a, 0, i, i + 1, $|a| - 1) \land$ sorted(a, i, |a| - 1)

 $-1 \leq i < |a| \land 0 \leq j \leq i \land$ partitioned(a, 0, i, i + 1, |a| - 1) \land sorted(a, i, |a| - 1) partitioned(a, 0, j - 1, j, j) C₂ Example: Does BUBBLESORT return a sorted array? int [] BUBBLESORT(int[] a) { int i, j, t;for (i := |a| - 1; i > 0; i := i - 1) { for (j := 0; j < i; j := j + 1) { if (a[j] > a[j + 1]) {t := a[j]; a[j] := a[j + 1]; a[j + 1] := t}; }} return a}

Generate verification conditions and prove that they are valid **Predicates**:

- sorted(a, l, u): $\forall i, j(l \le i \le j \le u \rightarrow a[i] \le a[j])$
- partitioned(a, l_1 , u_1 , l_2 , u_2): $\forall i, j(l_1 \leq i \leq u_1 \leq l_2 \leq j \leq u_2 \rightarrow a[i] \leq a[j])$

To prove: $C_2(a) \wedge \text{Update}(a, a') \rightarrow C_2(a')$

Another Situation

Insertion of an element c in a sorted array a of length n

for
$$(i := 1; i \le n; i := i + 1)$$
 {
if $a[i] \ge c\{n := n + 1$
for $(j := n; j > i; j := j - 1)\{a[i] := a[i - 1]\}$
 $a[i] := c;$ return a
}} $a[n + 1] := c;$ return a

Task:

If the array was sorted before insertion it is sorted also after insertion.

 $Sorted(a, n) \land Update(a, n, a', n') \land \neg Sorted(a', n') \models_{\mathcal{T}} \perp ?$

Task:

If the array was sorted before insertion it is sorted also after insertion.

$$\mathsf{Sorted}(a, n) \land \mathsf{Update}(a, n, a', n') \land \neg \mathsf{Sorted}(a', n') \models_{\mathcal{T}} \bot ?$$

Sorted(a, n)

$$\forall i, j(1 \le i \le j \le n \to a[i] \le a[j])$$

$$\forall pdate(a, n, a', n') \quad \forall i((1 \le i \le n \land a[i] < c) \to a'[i] = a[i])$$

$$\forall i((c \le a(1) \to a'[1] := c)$$

$$\forall i((a[n] < c \to a'[n+1] := c)$$

$$\forall i((1 \le i - 1 \le i \le n \land a[i - 1] < c \land a[i] \ge c) \to (a'[i] = c)$$

$$\forall i((1 \le i - 1 \le i \le n \land a[i - 1] \ge c \land a[i] \ge c \to a'[i] := a[i - 1]$$

$$\forall i((1 \le i - 1 \le i \le n \land a[i - 1] \ge c \land a[i] \ge c \to a'[i] := a[i - 1]$$

$$n' := n + 1$$

 $\neg \mathsf{Sorted}(a', n') \qquad \exists k, l(1 \le k \le l \le n' \land a'k] > a'[l])$

Extension: New arrays defined by case distinction – Def(f')

 $\forall \overline{x}(\phi_i(\overline{x}) \to f'(\overline{x}) = s_i(\overline{x})) \qquad i \in I, \text{ where } \phi_i(\overline{x}) \land \phi_j(\overline{x}) \models_{\mathcal{T}_0} \bot \text{ for } i \neq j(1)$ $\forall \overline{x}(\phi_i(\overline{x}) \to t_i(\overline{x}) \leq f'(\overline{x}) \leq s_i(\overline{x})) \qquad i \in I, \text{ where } \phi_i(\overline{x}) \land \phi_j(\overline{x}) \models_{\mathcal{T}_0} \bot \text{ for } i \neq j(2)$

where s_i , t_i are terms over the signature Σ such that $\mathcal{T}_0 \models \forall \overline{x}(\phi_i(\overline{x}) \rightarrow t_i(\overline{x}) \leq s_i(\overline{x}))$ for all $i \in I$.

 $\mathcal{T}_0 \subseteq \mathcal{T}_0 \land \mathsf{Def}(f')$ has the property that for every set G of ground clauses in which there are no nested applications of f':

 $\mathcal{T}_0 \wedge \mathrm{Def}(f') \wedge G \models \perp \quad \mathrm{iff} \quad \mathcal{T}_0 \wedge \mathrm{Def}(f')[G] \wedge G$

(sufficient to use instances of axioms in Def(f') which are relevant for G)

• Some of the syntactic restrictions of the array property fragment can be lifted

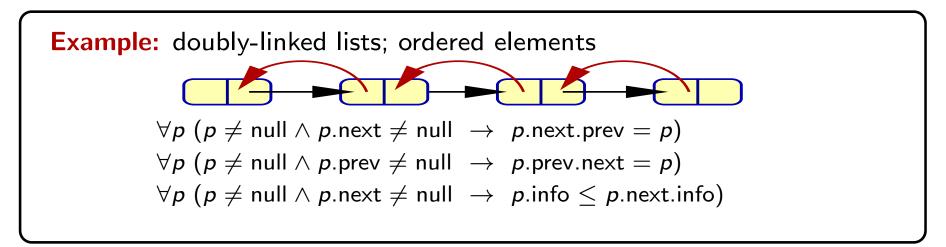
Insertion in an array

(on the blackboard)

[McPeak, Necula 2005]

- pointer sort p, scalar sort s; pointer fields $(p \rightarrow p)$; scalar fields $(p \rightarrow s)$;
- axioms: $\forall p \ \mathcal{E} \lor \mathcal{C}$; \mathcal{E} contains disjunctions of pointer equalities \mathcal{C} contains scalar constraints

Assumption: If $f_1(f_2(...f_n(p)))$ occurs in axiom, the axiom also contains: p=null $\lor f_n(p)=$ null $\lor \cdots \lor f_2(...f_n(p)))=$ null



[McPeak, Necula 2005]

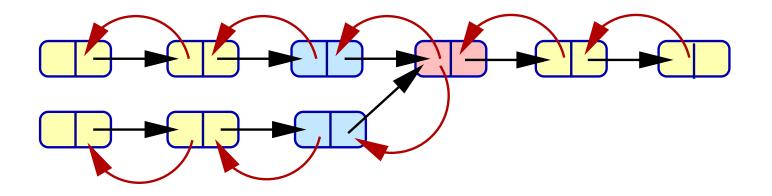
- pointer sort p, scalar sort s; pointer fields $(p \rightarrow p)$; scalar fields $(p \rightarrow s)$;
- axioms: $\forall p \ \mathcal{E} \lor \mathcal{C}$; \mathcal{E} contains disjunctions of pointer equalities \mathcal{C} contains scalar constraints

Assumption: If $f_1(f_2(...f_n(p)))$ occurs in axiom, the axiom also contains: p=null $\lor f_n(p)=$ null $\lor \cdots \lor f_2(...f_n(p)))=$ null

Theorem. K set of clauses in the fragment above. Then for every set G of ground clauses, $(K \cup G) \cup \mathcal{T}_s \models \perp$ iff $K^{[G]} \cup \mathcal{T}_s \models \perp$

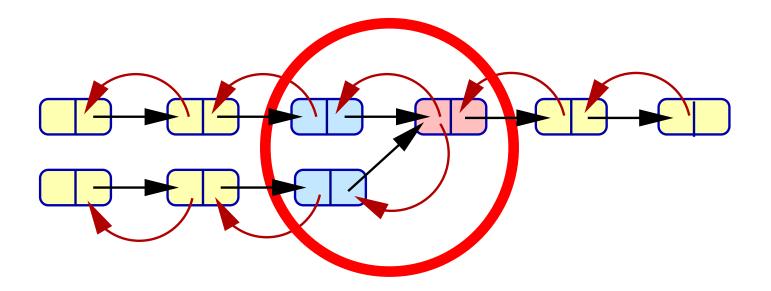
where $K^{[G]}$ is the set of instances of K in which the variables are replaced by subterms in G.

Example: A theory of doubly-linked lists



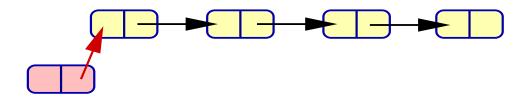
- $\forall p \ (p \neq \text{null} \land p.\text{next} \neq \text{null} \rightarrow p.\text{next.prev} = p)$ $\forall p \ (p \neq \text{null} \land p.\text{prev} \neq \text{null} \rightarrow p.\text{prev.next} = p)$
- $\land \ c \neq \mathsf{null} \land c.\mathsf{next} \neq \mathsf{null} \land d \neq \mathsf{null} \land d.\mathsf{next} \neq \mathsf{null} \land c.\mathsf{next} = d.\mathsf{next} \land c \neq d \quad \models \quad \bot$

Example: A theory of doubly-linked lists



 $(c \neq \mathsf{null} \land c.\mathsf{next} \neq \mathsf{null} \rightarrow c.\mathsf{next}.\mathsf{prev} = c) \quad (c.\mathsf{next} \neq \mathsf{null} \land c.\mathsf{next}.\mathsf{next} \neq \mathsf{null} \rightarrow c.\mathsf{next}.\mathsf{next}.\mathsf{prev} = c.\mathsf{next}.\mathsf{next} \neq \mathsf{null} \rightarrow d.\mathsf{next}.\mathsf{next}.\mathsf{prev} = d.\mathsf{next}.\mathsf{next} \neq \mathsf{null} \rightarrow d.\mathsf{next}.\mathsf{next}.\mathsf{prev} = d.\mathsf{next}$

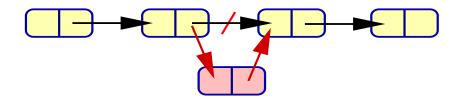
 $\land c \neq \mathsf{null} \land c.\mathsf{next} \neq \mathsf{null} \land d \neq \mathsf{null} \land d.\mathsf{next} \neq \mathsf{null} \land c.\mathsf{next} = d.\mathsf{next} \land c \neq d \models \bot$



Initially list is sorted: p.next \neq null \rightarrow p.prio \geq p.next.prio

c.prio = x, c.next = nullfor all $p \neq c$ do if $p.prio \leq x$ then if First(p) then c.next' = p, First'(c), \neg First'(p) endif; p.next' = p.next p.prio > x then case p.next = null then p.next' := c, c.next' = null $p.next \neq null \land p.next.prio > x$ then p.next' = p.next $p.next \neq null \land p.next.prio \leq x$ then p.next' = c, c.next' = p.next

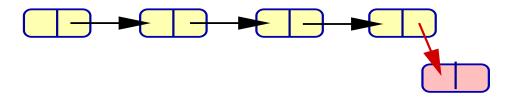
Verification task: After insertion list remains sorted



Initially list is sorted: p.next \neq null \rightarrow p.prio \geq p.next.prio

c.prio = x, c.next = nullfor all $p \neq c$ do if $p.prio \leq x$ then if First(p) then c.next' = p, First'(c), $\neg First'(p)$ endif; p.next' = p.next p.prio > x then case p.next = null then p.next' := c, c.next' = null $p.next \neq null \land p.next.prio > x$ then p.next' = p.next $p.next \neq null \land p.next.prio \leq x$ then p.next' = c, c.next' = p.next

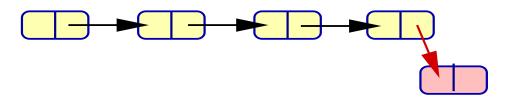
Verification task: After insertion list remains sorted



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Verification task: After insertion list remains sorted



Initially list is sorted: $\forall p(p.\text{next} \neq \text{null} \rightarrow p.\text{prio} \geq p.\text{next.prio})$

 $\forall p(p \neq \text{null} \land p \neq c \land \text{prio}(p) \leq x \land \text{First}(p) \rightarrow \text{next}'(c) = p \land \text{First}'(c)) \\ \forall p(p \neq \text{null} \land p \neq c \land \text{prio}(p) \leq x \land \text{First}(p) \rightarrow \text{next}'(p) = \text{next}(p) \land \neg \text{First}'(p))$

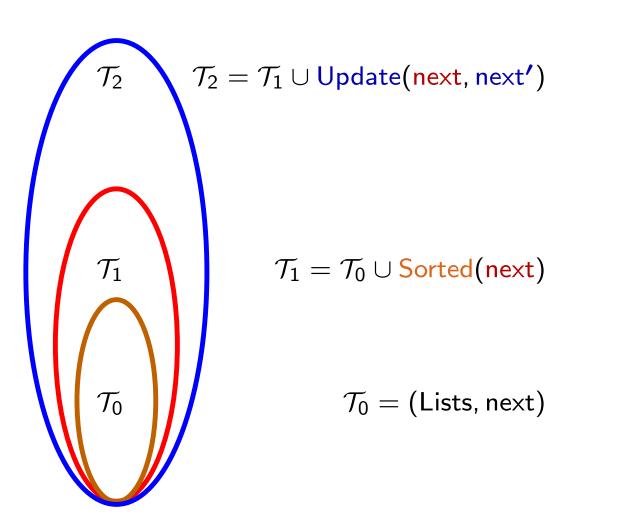
 $\forall p(p \neq \text{null} \land p \neq c \land \text{prio}(p) \leq x \land \neg \text{First}(p) \rightarrow \text{next}'(p) = \text{next}(p))$

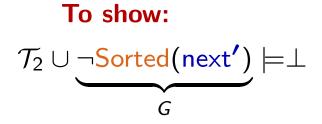
 $\forall p(p \neq \text{null} \land p \neq c \land \text{prio}(p) > x \land \text{next}(p) = \text{null} \rightarrow \text{next}'(p) = c$ $\forall p(p \neq \text{null} \land p \neq c \land \text{prio}(p) > x \land \text{next}(p) = \text{null} \rightarrow \text{next}'(c) = \text{null})$

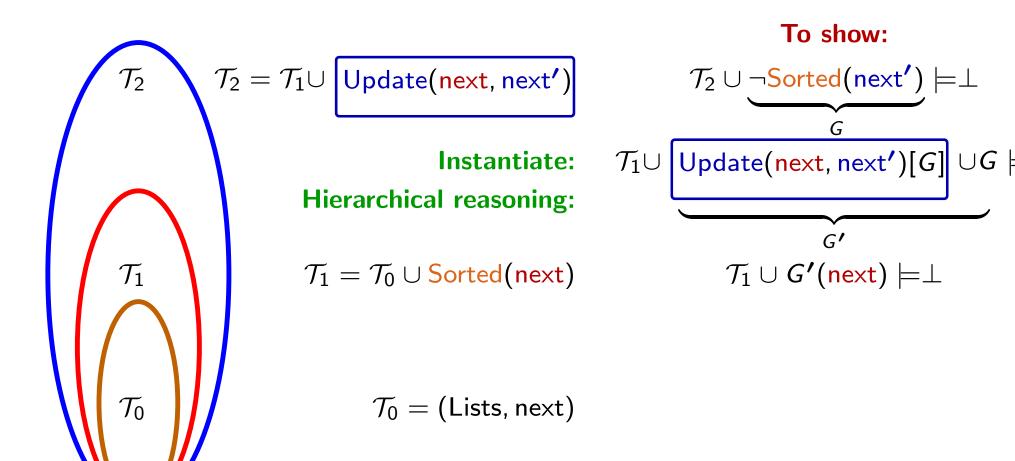
 $\forall p(p \neq \text{null} \land p \neq c \land \text{prio}(p) > x \land \text{next}(p) \neq \text{null} \land \text{prio}(\text{next}(p)) > x \rightarrow \text{next}'(p) = \text{next}(p))$

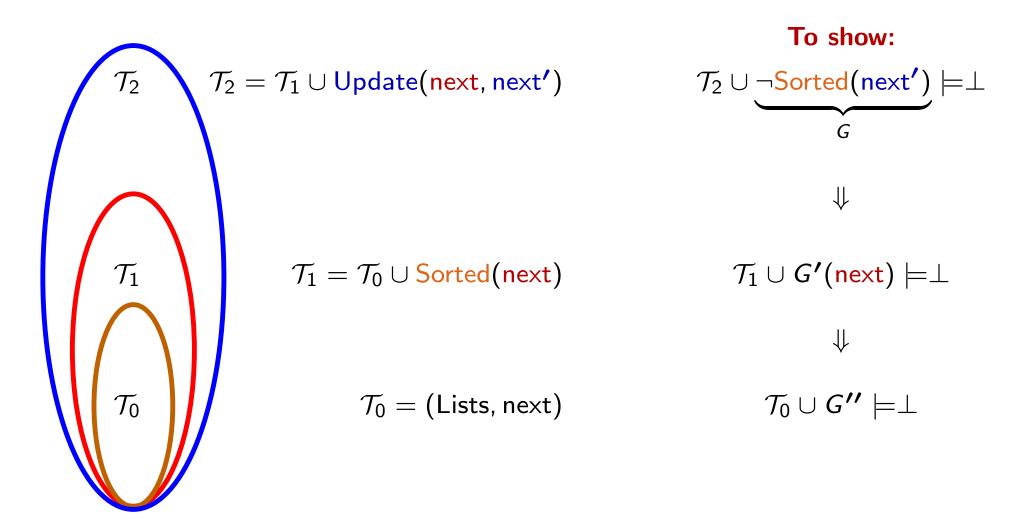
 $\forall p(p \neq \text{null} \land p)$ We only need to use instances in which variables are
replaced by ground subterms occurring in the problem(p)=c
(c)=next(p))

To check: Sorted(next, prio) \land Update(next, next') \land p_0 .next' \neq null \land p_0 .prio \geq p_0 .next'.prio $\models \perp$









More general concept

Local Theory Extensions

Satisfiability of formulae with quantifiers

Goal: generalize the ideas for extensions of theories

$$\mathbb{R} \cup \mathbb{Z} \cup \mathsf{Mon}(f) \cup \underbrace{(a < b \land f(a) = f(b) + 1)}_{G} \models \bot$$

$$Mon(f) \qquad \forall i, j(i < j \rightarrow f(i) < f(j))$$

Problems:

- A prover for $\mathbb{R} \cup \mathbb{Z}$ does not know about f
- A prover for first-order logic may have problems with the reals and integers
- DPLL(T) cannot be used (Mon, \mathbb{Z}, \mathbb{R} : non-disjoint signatures)
- SMT provers may have problems with the universal quantifiers

Our goal: reduce search: consider certain instances Mon(f)[G]without loss of completeness hierarchical/modular reasoning: reduce to checking satisfiability of a set of constraints over $\mathbb{R} \cup \mathbb{Z}$ Solution: Local theory extensions

 \mathcal{K} set of equational clauses; \mathcal{T}_0 theory; $\mathcal{T}_1 = \mathcal{T}_0 \cup \mathcal{K}$

(Loc) $\mathcal{T}_0 \subseteq \mathcal{T}_1$ is local, if for ground clauses G, $\mathcal{T}_0 \cup \mathcal{K} \cup G \models \perp \text{ iff } \mathcal{T}_0 \cup \mathcal{K}[G] \cup G \text{ has no (partial) model}$

Various notions of locality, depending of the instances to be considered: stable locality, order locality; extended locality.

$$\mathbb{R} \cup \mathbb{Z} \cup \mathsf{Mon}(f) \cup \underbrace{(a < b \land f(a) = f(b) + 1)}_{G} \models \perp$$

Base theory
$$(\mathbb{R} \cup \mathbb{Z})$$
Extension $a < b$ $f(a) = f(b) + 1$ $\forall i, j(i < j \rightarrow f(i) < f(j))$

$$\mathbb{R} \cup \mathbb{Z} \cup \mathsf{Mon}(f) \cup \underbrace{(a < b \land f(a) = f(b) + 1)}_{G} \models \perp$$

Extension is local \mapsto replace axiom with ground instances

Base theory $(\mathbb{R}\cup\mathbb{Z})$	Extension	
a < b	$egin{aligned} f(a) &= f(b) + 1 \ a &< b ightarrow f(a) &< f(b) \ b &< a ightarrow f(b) &< f(a) \end{aligned}$	Solution 1: $SMT(\mathbb{R} \cup \mathbb{Z} \cup UIF)$

$$\mathbb{R} \cup \mathbb{Z} \cup \mathsf{Mon}(f) \cup \underbrace{(a < b \land f(a) = f(b) + 1)}_{G} \models \bot$$

Extension is local \mapsto replace axiom with ground instances

Add congruence axioms. Replace pos-terms with new constants

Base theory $(\mathbb{R}\cup\mathbb{Z})$	Extension	
a < b	$egin{aligned} f(a) &= f(b) + 1 \ a &< b ightarrow f(a) &< f(b) \ b &< a ightarrow f(b) &< f(a) \ a &= b ightarrow f(a) &= f(b) \end{aligned}$	Solution 2:
	$b < a \rightarrow f(b) < f(a)$	Hierarchical reasoning
	a = b ightarrow f(a) = f(b)	

$$\mathbb{R} \cup \mathbb{Z} \cup \mathsf{Mon}(f) \cup \underbrace{(a < b \land f(a) = f(b) + 1)}_{G} \models \perp$$

Extension is local \mapsto replace axiom with ground instances

Replace *f*-terms with new constants

Add definitions for the new constants

Base theory $(\mathbb{R}\cup\mathbb{Z})$	Extension
a < b	$a_1 = b_1 + 1$
	$a < b o a_1 < b_1$
	$egin{array}{llllllllllllllllllllllllllllllllllll$
	$a=b o a_1=b_1$

$$\mathbb{R} \cup \mathbb{Z} \cup \mathsf{Mon}(f) \cup \underbrace{(a < b \land f(a) = f(b) + 1)}_{G} \models \bot$$

Extension is local \mapsto replace axiom with ground instances

Replace *f*-terms with new constants

Add definitions for the new constants

Base theory $(\mathbb{R}\cup\mathbb{Z})$	Extension	
a < b	$a_1 = f(a)$	
$a_1=b_1+1$	$b_1 = f(b)$	
$a < b o a_1 < b_1$		
$b < a ightarrow b_1 < a_1$		
$a=b ightarrow a_1=b_1$		

Reasoning in local theory extensions

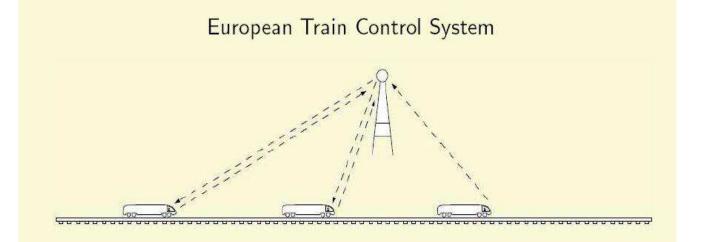
Locality: $\mathcal{T}_0 \cup \mathcal{K} \cup G \models \perp$ iff $\mathcal{T}_0 \cup \mathcal{K}[G] \cup G \models \perp$

Problem: Decide whether $\mathcal{T}_0 \cup \mathcal{K}[G] \cup G \models \perp$

Solution 1: Use $SMT(\mathcal{T}_0+UIF)$: possible only if $\mathcal{K}[G]$ ground

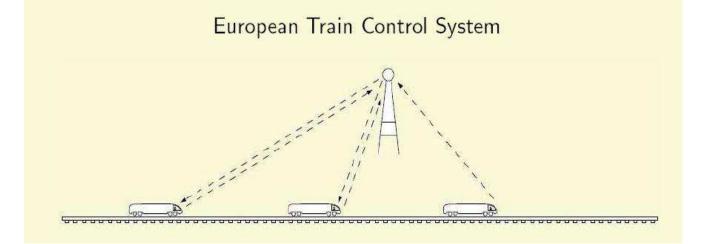
Solution 2: Hierarchic reasoning [VS'05] reduce to satisfiability in \mathcal{T}_0 : applicable in general \mapsto parameterized complexity

Simplified version of ETCS Case Study [Jacobs, VS'06, Faber, Jacobs, VS'07]



Number of trains:	<i>n</i> ≥ 0	\mathbb{Z}
Minimum and maximum speed of trains:	$0 \leq \min < \max$	\mathbb{R}
Minimum secure distance:	$I_{\rm alarm} > 0$	\mathbb{R}
Time between updates:	$\Delta t > 0$	\mathbb{R}
Train positions before and after update:	pos (i), pos' (i)	$:\mathbb{Z} ightarrow \mathbb{R}$

Simplified version of ETCS Case Study [Jacobs, VS'06, Faber, Jacobs, VS'07]

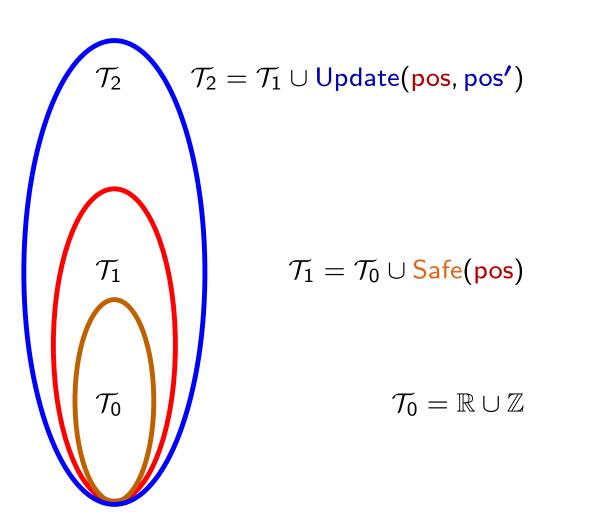


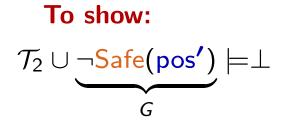
Safety property: No collisions $Safe(pos) : \forall i, j(i < j \rightarrow pos(i) > pos(j))$

Inductive invariant: Safe(pos) \land Update(pos, pos') $\land \neg$ Safe(pos') $\models_{\mathcal{T}_S} \bot$

where \mathcal{T}_S is the extension of the (disjoint) combination $\mathbb{R} \cup \mathbb{Z}$ with two functions, pos, pos' : $\mathbb{Z} \to \mathbb{R}$

Our idea: Use chains of "instantiation" + reduction.





$$\mathcal{T}_{2} \qquad \mathcal{T}_{2} = \mathcal{T}_{1} \cup \mathsf{Update}(\mathsf{pos},\mathsf{pos'}) \qquad \mathcal{T}_{2} \cup \underbrace{\neg \mathsf{Safe}(\mathsf{pos'})}_{G} \models \bot \\ \downarrow \\ \mathcal{T}_{1} \qquad \mathcal{T}_{1} = \mathcal{T}_{0} \cup \mathsf{Safe}(\mathsf{pos}) \qquad \mathcal{T}_{1} \cup \mathcal{G}'(\mathsf{pos}) \models \bot \\ \downarrow \\ \mathcal{T}_{0} \qquad \qquad \mathcal{T}_{0} = \mathbb{R} \cup \mathbb{Z} \qquad \mathcal{T}_{0} \cup \mathcal{G''} \models \bot \\ \Phi(c, \overline{c}_{\mathsf{pos'}}, \overline{d}_{\mathsf{pos}}, n, l_{\mathsf{alarm}}, \mathsf{min}, \mathsf{max}, \Delta t) \models_{-} \\ \end{bmatrix}$$
Method 1: SAT checking/ Counterexample generation

Method 2: Quantifier elimination

relationships between parameters which guarantee safety

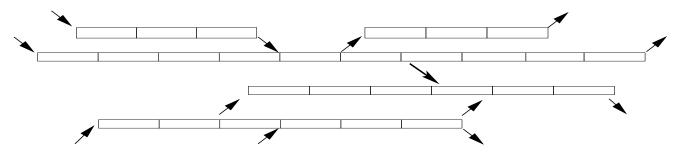
More complex ETCS Case studies

[Faber, Jacobs, VS, 2007]

- Take into account also:
 - Emergency messages
 - Durations
- Specification language: CSP-OZ-DC
 - Reduction to satisfiability in theories for which decision procedures exist
- Tool chain: [Faber, Ihlemann, Jacobs, VS]
 CSP-OZ-DC → Transition constr. → Decision procedures (H-PILoT)

Example 2: Parametric topology

• Complex track topologies [Faber, Ihlemann, Jacobs, VS, ongoing work]

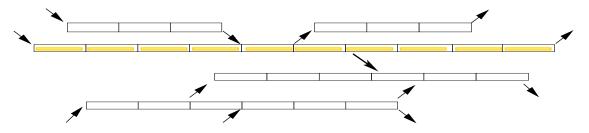


Assumptions:

- No cycles
- in-degree (out-degree) of associated graph at most 2.

Parametricity and modularity

• Complex track topologies [Faber, Ihlemann, Jacobs, VS, ongoing work]



Assumptions:

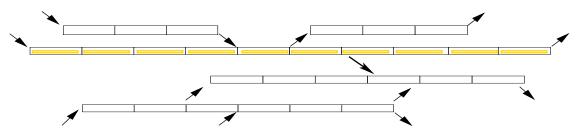
- No cycles
- in-degree (out-degree) of associated graph at most 2.

Approach:

- Decompose the system in trajectories (linear rail tracks; may overlap)
- Task 1: Prove safety for trajectories with incoming/outgoing trains
 - Conclude that for control rules in which trains have sufficient freedom (and if trains are assigned unique priorities) safety of all trajectories implies safety of the whole system
- Task 2: General constraints on parameters which guarantee safety

Parametricity and modularity

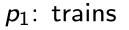
• Complex track topologies [Faber, Ihlemann, Jacobs, VS, ongoing work]



Assumptions:

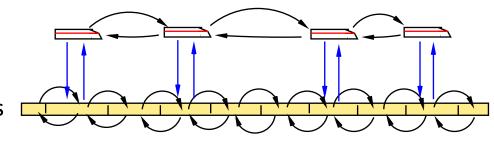
- No cycles
- in-degree (out-degree) of associated graph at most 2.

Data structures:

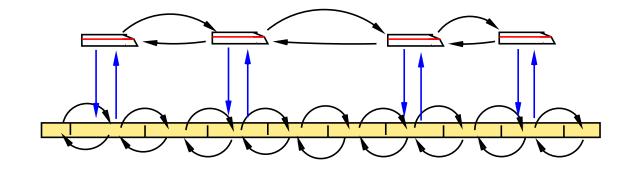


• 2-sorted pointers

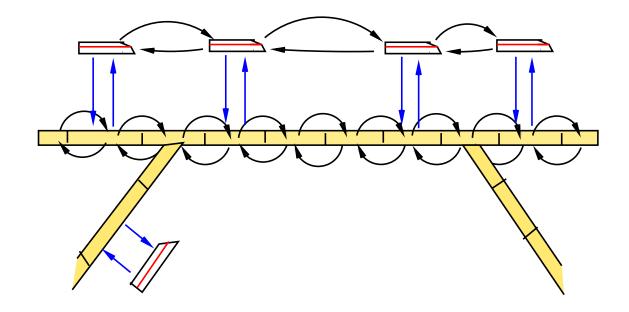
 p_2 : segments

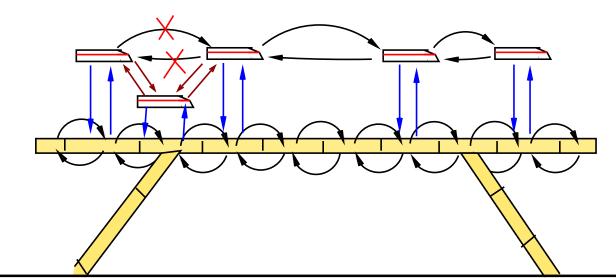


- scalar fields $(f:p_i \rightarrow \mathbb{R}, g:p_i \rightarrow \mathbb{Z})$
- updates efficient decision procedures (H-PiLoT)



Example 1: Speed Update $pos(t) < length(segm(t)) - d \rightarrow 0 \leq spd'(t) \leq lmax(segm(t))$ $pos(t) \geq length(segm(t)) - d \wedge alloc(next_s(segm(t))) = tid(t)$ $\rightarrow 0 \leq spd'(t) \leq min(lmax(segm(t)), lmax(next_s(segm(t))))$ $pos(t) \geq length(segm(t)) - d \wedge alloc(next_s(segm(t))) \neq tid(t)$ $\rightarrow spd'(t) = max(spd(t) - decmax, 0)$



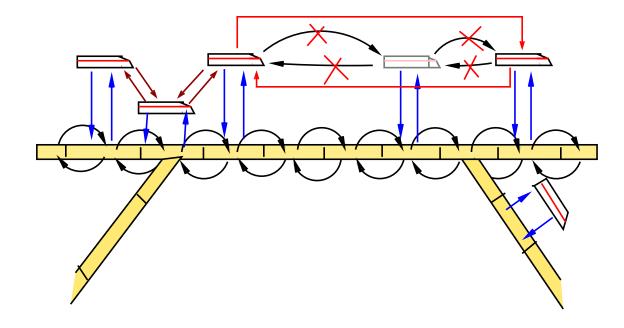


Example 2: Enter Update (also updates for segm', spd', pos', train')

Assume: $s_1 \neq \text{null}_s$, $t_1 \neq \text{null}_t$, train $(s) \neq t_1$, alloc $(s_1) = \text{idt}(t_1)$

 $t \neq t_1$, ids(segm(t))<ids(s_1), next_t(t)=null_t, alloc(s_1)=tid(t_1) \rightarrow next'(t)= $t_1 \land$ next'(t_1)=null_t $t \neq t_1$, ids(segm(t))<ids(s_1), alloc(s_1)=tid(t_1), next_t(t) \neq null_t, ids(segm(next_t(t))) \leq ids(s_1) \rightarrow next'(t)=next_t(t)

 $t \neq t_1$, ids(segm(t)) \geq ids(s_1) \rightarrow next'(t)=next_t(t)



Safety property

Safety property we want to prove: no two trains ever occupy the same track segment:

$$(\mathsf{Safe}) := \forall t_1, t_2 \; \mathsf{segm}(t_1) = \mathsf{segm}(t_2) \rightarrow t_1 = t_2$$

In order to prove that (Safe) is an invariant of the system, we need to find a suitable invariant (Inv(i)) for every control location i of the TCS, and prove:

$$(Inv(i)) \models (Safe)$$
 for all locations *i*

and that the invariants are preserved under all transitions of the system,

$$(\mathsf{Inv}(i)) \land (\mathsf{Update}) \models (\mathsf{Inv}'(j))$$

whenever (Update) is a transition from location i to j .

Safety property

Need additional invariants.

- generate by hand [Faber, Ihlemann, Jacobs, VS, ongoing]
 - use the capabilities of H-PILoT of generating counterexamples
- generate automatically [work in progress]

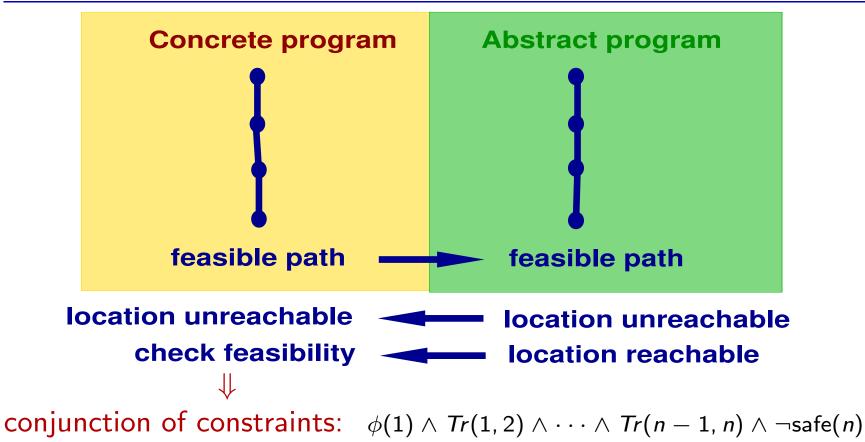
Ground satisfiability problems for pointer data structures

the decision procedures presented before can be used without problems

Other interesting topics

- Generate invariants
- Verification by abstraction/refinement

Abstraction-based Verification



- satisfiable: feasible path

unsatisfiable: refine abstract program s.t. the path is not feasible
 [McMillan 2003-2006] use 'local causes of inconsistency'
 → compute interpolants

Summary

• Decision procedures for various theories/theory combinations

Implemented in most of the existing SMT provers: Z3: http://z3.codeplex.com/ CVC4: http://cvc4.cs.nyu.edu/web/ Yices: http://yices.csl.sri.com/

• Ideas about how to use them for verification

Decision procedures for other classes of theories/Applications"

Next semester: Seminar "Decision Procedures and Applications"

More details on Specification, Model Checking, Verification:

This summer (end of August):

Summer school "Verification Technology, Systems & Applications" Next year: Lecture "Formal Specification and Verification"

Forschungspraktika BSc/MSc Theses in the area