

# Decision Procedures for Verification

First-Order Logic (4)

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# Until now:

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**Syntax** (one-sorted signatures vs. many-sorted signatures)

## **Semantics**

Structures (also many-sorted)

Models, Validity, and Satisfiability

Entailment and Equivalence

**Theories (Syntactic vs. Semantics view)**

**Algorithmic Problems:** Check satisfiability

# Until now:

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**Normal Forms**

**Herbrand Models**

decidability of the Bernays-Schönkinkel class

**Resolution**

## 2.8 Ordered Resolution with Selection

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Motivation: Search space for *Res* very large.

Ideas for improvement:

1. In the completeness proof (Model Existence Theorem) one only needs to resolve and factor maximal atoms  
⇒ if the calculus is restricted to inferences involving maximal atoms, the proof remains correct  
⇒ *order restrictions*
2. In the proof, it does not really matter with which negative literal an inference is performed  
⇒ choose a negative literal don't-care-nondeterministically  
⇒ *selection*

# Selection Functions

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A **selection function** is a mapping

$$S : C \mapsto \text{set of occurrences of } \textit{negative} \text{ literals in } C$$

Example of selection with selected literals indicated as  $\boxed{X}$ :

$$\boxed{\neg A} \vee \neg A \vee B$$
$$\boxed{\neg B_0} \vee \boxed{\neg B_1} \vee A$$

# Resolution Calculus $Res_{\succ}$

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In the completeness proof, we talk about (strictly) maximal literals of *ground* clauses.

In the non-ground calculus, we have to consider those literals that correspond to (strictly) maximal literals of ground instances:

Let  $\succ$  be a total and well-founded ordering on ground atoms.

A literal  $L$  is called **[strictly] maximal** in a clause  $C$  if and only if there exists a ground substitution  $\sigma$  such that for all  $L'$  in  $C$ :  $L\sigma \succeq L'\sigma$  [ $L\sigma \succ L'\sigma$ ].

# Resolution Calculus $Res_S^\succ$

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Let  $\succ$  be an atom ordering and  $S$  a selection function.

$$\frac{C \vee A \quad \neg B \vee D}{(C \vee D)\sigma} \quad [\text{ordered resolution with selection}]$$

if  $\sigma = \text{mgu}(A, B)$  and

- (i)  $A\sigma$  strictly maximal wrt.  $C\sigma$ ;
- (ii) nothing is selected in  $C$  by  $S$ ;
- (iii) either  $\neg B$  is selected,  
or else nothing is selected in  $\neg B \vee D$  and  $\neg B\sigma$  is maximal in  $D\sigma$ .

# Resolution Calculus $Res_{\mathcal{S}}$

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$$\frac{C \vee A \vee B}{(C \vee A)\sigma}$$

[ordered factoring]

if  $\sigma = \text{mgu}(A, B)$  and  $A\sigma$  is maximal in  $C\sigma$  and nothing is selected in  $C$ .



# Soundness and Refutational Completeness

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## Theorem 2.27:

Let  $\succ$  be an atom ordering and  $S$  a selection function such that  $\text{Res}_S^\succ(N) \subseteq N$ . Then

$$N \models \perp \Leftrightarrow \perp \in N$$

Proof:

The “ $\Leftarrow$ ” part is trivial. For the “ $\Rightarrow$ ” part consider first the propositional level: Construct a candidate model  $I_N$  as for unrestricted resolution, except that clauses  $C$  in  $N$  that have selected literals are not productive, even when they are false in  $I_C$  and when their maximal atom occurs only once and positively.

The result for general clauses follows using the lifting lemma.

# Redundancy

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So far: local restrictions of the resolution inference rules using orderings and selection functions.

Is it also possible to delete clauses altogether?

Under which circumstances are clauses unnecessary?

(Conjecture: e. g., if they are tautologies or if they are subsumed by other clauses.)

**Intuition:** If a clause is guaranteed to be neither a minimal counterexample nor productive, then we do not need it.

# Recall

Construction of  $I$  for the extended clause set:

	clauses $C$	$I_C$	$\Delta_C$	Remarks
1	$\neg P_0$	$\emptyset$	$\emptyset$	
2	$P_0 \vee P_1$	$\emptyset$	$\{P_1\}$	
3	$P_1 \vee P_2$	$\{P_1\}$	$\emptyset$	
4	$\neg P_1 \vee P_2$	$\{P_1\}$	$\{P_2\}$	
9	$\neg P_1 \vee \neg P_1 \vee P_3 \vee P_0$	$\{P_1, P_2\}$	$\{P_3\}$	
8	$\neg P_1 \vee \neg P_1 \vee P_3 \vee P_3 \vee P_0$	$\{P_1, P_2, P_3\}$	$\emptyset$	true in $\mathcal{A}_C$
5	$\neg P_1 \vee P_4 \vee P_3 \vee P_0$	$\{P_1, P_2, P_3\}$	$\emptyset$	
6	$\neg P_1 \vee \neg P_4 \vee P_3$	$\{P_1, P_2, P_3\}$	$\emptyset$	true in $\mathcal{A}_C$
7	$\neg P_3 \vee P_5$	$\{P_1, P_2, P_3\}$	$\{P_5\}$	

The resulting  $I = \{P_1, P_2, P_3, P_5\}$  is a model of the clause set.

# A Formal Notion of Redundancy

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Let  $N$  be a set of ground clauses and  $C$  a ground clause (not necessarily in  $N$ ).  $C$  is called **redundant** w. r. t.  $N$ , if there exist  $C_1, \dots, C_n \in N$ ,  $n \geq 0$ , such that  $C_i \prec C$  and  $C_1, \dots, C_n \models C$ .

Redundancy for general clauses:

$C$  is called **redundant** w. r. t.  $N$ , if all ground instances  $C\sigma$  of  $C$  are redundant w. r. t.  $G_\Sigma(N)$ .

**Intuition:** Redundant clauses are neither minimal counterexamples nor productive.

**Note:** The same ordering  $\succ$  is used for ordering restrictions and for redundancy (and for the completeness proof).

# Examples of Redundancy

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## Proposition 2.28:

- $C$  tautology (i.e.,  $\models C$ )  $\Rightarrow$   $C$  redundant w. r. t. any set  $N$ .
- $C\sigma \subset D$   $\Rightarrow$   $D$  redundant w. r. t.  $N \cup \{C\}$

(Under certain conditions one may also use non-strict subsumption, but this requires a slightly more complicated definition of redundancy.)

# Saturation up to Redundancy

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$N$  is called **saturated up to redundancy** (wrt.  $Res_S^>$ )

$$:\Leftrightarrow Res_S^>(N \setminus Red(N)) \subseteq N \cup Red(N)$$

## Theorem 2.29:

Let  $N$  be saturated up to redundancy. Then

$$N \models \perp \Leftrightarrow \perp \in N$$

# Saturation up to Redundancy

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Proof (Sketch):

(i) Ground case:

- consider the construction of the candidate model  $I_N^>$  for  $Res_S^>$
- redundant clauses are not productive
- redundant clauses in  $N$  are not minimal counterexamples for  $I_N^>$

The premises of “essential” inferences are either minimal counterexamples or productive.

(ii) Lifting: no additional problems over the proof of Theorem 2.27.

# Monotonicity Properties of Redundancy

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## Theorem 2.30:

$$(i) \quad N \subseteq M \Rightarrow Red(N) \subseteq Red(M)$$

$$(ii) \quad M \subseteq Red(N) \Rightarrow Red(N) \subseteq Red(N \setminus M)$$

## Proof:

(i) Let  $C \in Red(N)$ . Then there exist  $C_1, \dots, C_n \in N, n \geq 0$  such that  $C_i \prec C$  for all  $i = 1, \dots, n$  and  $C_1, \dots, C_n \Vdash C$ .

We assumed that  $N \subseteq M$ , so we know that  $C_1, \dots, C_n \in M$ .

Thus: there exist  $C_1, \dots, C_n \in M, n \geq 0$  such that  $C_i \prec C$  for all  $i = 1, \dots, n$  and  $C_1, \dots, C_n \Vdash C$ . Therefore,  $C \in Red(M)$ .



# Monotonicity Properties of Redundancy

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$$(i) \quad N \subseteq M \Rightarrow Red(N) \subseteq Red(M)$$

$$(ii) \quad M \subseteq Red(N) \Rightarrow Red(N) \subseteq Red(N \setminus M)$$

Proof (Idea):

(ii) Let  $C \in Red(N)$ . Then there exist  $C_1, \dots, C_n \in N, n \geq 0$  such that  $C_i \prec C$  for all  $i = 1, \dots, n$  and  $C_1, \dots, C_n \models C$ .

Case 1: For all  $i, C_i \notin M$ . Then  $C \in Red(N \setminus M)$ .

Case 2: For some  $i, C_i \in M \subseteq Red(N)$ . Then for every such index  $i$  there exist  $C_1^i, \dots, C_{n_i}^i \in N$  such that  $C_j^i \prec C_i$  and  $C_1^i, \dots, C_{n_i}^i \models C_i$ . We can replace  $C_i$  above with  $C_1^i, \dots, C_{n_i}^i$ . We can iterate the procedure until none of the  $C_i$ 's are in  $M$  (termination guaranteed by the fact that  $\succ$  is well-founded).

# Some theorem provers for first-order logic

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- SPASS <http://www.spass-prover.org/>
- E <http://www4.informatik.tu-muenchen.de/~schulz/E/E.html>
- Vampire <http://www.vprover.org/>

Example (SPASS)

# Consequences

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## Corollary 2.22:

Let  $N$  be a set of general clauses saturated under  $Res$ , i.e.,  $Res(N) \subseteq N$ . Then also  $G_\Sigma(N)$  is saturated, that is,

$$Res(G_\Sigma(N)) \subseteq G_\Sigma(N).$$

## Lemma 2.23:

Let  $N$  be a set of  $\Sigma$ -clauses, let  $\mathcal{A}$  be an interpretation. Then  $\mathcal{A} \models N$  implies  $\mathcal{A} \models G_\Sigma(N)$ .

## Lemma 2.24:

Let  $N$  be a set of  $\Sigma$ -clauses, let  $\mathcal{A}$  be a *Herbrand* interpretation. Then  $\mathcal{A} \models G_\Sigma(N)$  implies  $\mathcal{A} \models N$ .

# Consequences

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## Theorem (Herbrand's theorem):

A set  $N$  of  $\Sigma$ -clauses is satisfiable if and only if it has a Herbrand model over  $\Sigma$ .

Proof:

The “ $\Leftarrow$ ” part is trivial. For the “ $\Rightarrow$ ” part let  $N \not\models \perp$ .

$$N \not\models \perp \Rightarrow \perp \notin \text{Res}^*(N) \quad (\text{resolution is sound})$$

$$\Rightarrow \perp \notin G_\Sigma(\text{Res}^*(N))$$

$$\Rightarrow I_{G_\Sigma(\text{Res}^*(N))} \models G_\Sigma(\text{Res}^*(N)) \quad (\text{Lemma. 2.23; Cor. 2.22})$$

$$\Rightarrow I_{G_\Sigma(\text{Res}^*(N))} \models \text{Res}^*(N) \quad (\text{Lemma 2.24})$$

$$\Rightarrow I_{G_\Sigma(\text{Res}^*(N))} \models N \quad (N \subseteq \text{Res}^*(N))$$

# The Theorem of Löwenheim-Skolem

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## Theorem 2.31 (Löwenheim–Skolem):

Let  $\Sigma$  be a countable signature and let  $S$  be a set of closed  $\Sigma$ -formulas. Then  $S$  is satisfiable iff  $S$  has a model over a countable universe.

Proof:

If both  $X$  and  $\Sigma$  are countable, then  $S$  can be at most countably infinite. Now generate, maintaining satisfiability, a set  $N$  of clauses from  $S$ . This extends  $\Sigma$  by at most countably many new Skolem functions to  $\Sigma'$ . As  $\Sigma'$  is countable, so is  $T_{\Sigma'}$ , the universe of Herbrand-interpretations over  $\Sigma'$ . Now apply Theorem 2.25 (Herbrand's theorem).

# Compactness of Predicate Logic

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**Theorem 2.32** (Compactness Theorem for First-Order Logic):

Let  $\Phi$  be a set of first-order formulas.

$\Phi$  is unsatisfiable  $\Leftrightarrow$  some finite subset  $\Psi \subseteq \Phi$  is unsatisfiable.

Proof:

The “ $\Leftarrow$ ” part is trivial. For the “ $\Rightarrow$ ” part let  $\Phi$  be unsatisfiable and let  $N$  be the set of clauses obtained by Skolemization and CNF transformation of the formulas in  $\Phi$ . Clearly  $Res^*(N)$  is unsatisfiable.

Since resolution is complete,  $\perp \in Res^*(N)$ ,  $\perp \in Res^n(N)$  for some  $n \in \mathbb{N}$ . Consequently,  $\perp$  has a finite resolution proof  $B$  of depth  $\leq n$ . Choose  $\Psi$  as the subset of formulas in  $\Phi$  such that the corresponding clauses contain the assumptions (leaves) of  $B$ .

# Craig Interpolation

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A theoretical application of ordered resolution is **Craig Interpolation**:

## Theorem (Craig 57)

Let  $F$  and  $G$  be two propositional formulas such that  $F \models G$ .

Then there exists a formula  $H$  (called the interpolant for  $F \models G$ ), such that  $H$  contains only propositional variables occurring both in  $F$  and in  $G$ , and such that  $F \models H$  and  $H \models G$ .

# Craig Interpolation

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Proof:

Translate  $F$  and  $\neg G$  into CNF.

Let  $N$  and  $M$ , resp., denote the resulting clause set.

Choose an atom ordering  $\succ$  for which the propositional variables that occur in  $F$  but not in  $G$  are maximal.

Saturate  $N$  into  $N^*$  wrt.  $\text{Res}_S^\succ$  with an empty selection function  $S$ .

Then saturate  $N^* \cup M$  wrt.  $\text{Res}_S^\succ$  to derive  $\perp$ .

As  $N^*$  is already saturated, due to the ordering restrictions only inferences need to be considered where premises, if they are from  $N^*$ , only contain symbols that also occur in  $G$ .

The conjunction of these premises is an interpolant  $H$ .

The theorem also holds for first-order formulas. For universal formulas the above proof can be easily extended. In the general case, a proof based on resolution technology is more complicated because of Skolemization.



# Applications of Craig Interpolation

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## Modular databases

**Given:** Two databases (different but possibly overlapping languages)

**Task:** Is the union of the two databases consistent? If not: locate error

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$$F_1 \wedge F_2 \models \perp$$

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Craig Interpolation (propositional case)

There exists  $I$  containing only propositional variables occurring in  $F_1$  and  $F_2$  such that:

$$F_1 \models I \text{ and } I \models \neg F_2$$

# Applications of Craig Interpolation

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## Reasoning in combinations of theories

**Given:** Two theories (different but possibly overlapping languages)  
s.t. decision procedures for component theories for certain fragments exist

**Task:** Reason in the combination of the two theories

**Question:** Which information needs to be exchanged between provers?

**Answer:** Craig Interpolation

The case of two disjoint theories will be discussed later in this lecture

# Applications of Craig Interpolation

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## Verification (programs or hardware)

Model programs as transition systems.

- Sets of states expressed as formulae
- Transitions expressed as formulae  $T$

### Question:

Can a state in a certain set of states  $E$  (error) be reached from some state in a set  $I$  (initial) in  $k$  steps?

$$\phi_I \wedge T_1 \wedge T_2 \wedge \cdots \wedge T_k \wedge \phi_E$$

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Not reachable:  $F_1 \wedge F_2 \models \perp$

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**Interpolant:**  $I$  overapproximates the set of successors of  $\phi_I$ .



# Decidable subclasses of first-order logic

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# Applications

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Use ordered resolution with selection to give a decision procedure for the Ackermann class.

# The Ackermann class

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$\Sigma = (\Omega, \Pi)$ ,  $\Omega$  is a finite set of constants

The Ackermann class consists of all sentences of the form

$$\exists x_1 \dots \exists x_n \forall x \exists y_1 \dots \exists y_m F(x_1, \dots, x_n, x, y_1, \dots, y_m)$$

**Idea:** CNF translation:

$$\begin{aligned} & \exists x_1 \dots \exists x_n \forall x \exists y_1 \dots \exists y_m F(x_1, \dots, x_n, x, y_1, \dots, y_m) \\ & \Rightarrow_S \forall x F(\bar{c}_1, \dots, \bar{c}_n, x, f_1(x), \dots, f_m(x)) \\ & \Rightarrow_K \forall x \bigwedge \bigvee L_i(c_1, \dots, c_n, x, f_1(x), \dots, f_m(x)) \end{aligned}$$

$c_1, \dots, c_n$  are Skolem constants

$f_1, \dots, f_m$  are unary Skolem functions

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**Idea:** CNF translation:

$$\begin{aligned} &\exists x_1 \dots \exists x_n \forall x \exists y_1 \dots \exists y_m F(x_1, \dots, x_n, x, y_1, \dots, y_m) \\ &\Rightarrow^* \forall x \bigwedge \bigvee L_i(c_1, \dots, c_n, x, f_1(x), \dots, f_m(x)) \end{aligned}$$

The clauses are in the following classes:

$G = G(c_1, \dots, c_n)$  ground clauses without function symbols

$V = V(x, c_1, \dots, c_n)$  clauses with one variable and without function symbols

$G_f = G(c_1, \dots, c_n, f_1, \dots, f_n)$  ground clauses with function symbols

$V_f = V(x, c_1, \dots, c_n, f_1(x), \dots, f_n(x))$  clauses with a variable & function symbols

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$V_f = V(x, c_1, \dots, c_n, f_1(x), \dots, f_n(x))$  clauses with a variable & function symbols

## Term ordering

$f(t) \succ t$ ; terms containing function symbols larger than those who do not.

$B \succ A$  iff exists argument  $u$  of  $B$  such that every argument  $t$  of  $A$ :  $u \succ t$

**Ordered resolution:**  $G \cup V \cup G_f \cup V_f$  is closed under ordered resolution.

$G, G \mapsto G$ ;  $G, V \mapsto G$ ;  $G, G_f \mapsto$  nothing;  $G, V_f \mapsto$  nothing

$V, V \mapsto V \cup G$ ;  $V, G_f \mapsto G \cup G_f$ ;  $V, V_f \mapsto G \cup V \cup G_f \cup V_f$

$G_f, G_f \mapsto G_f$ ;  $G_f, V_f \mapsto G_f \cup G$ ;  $V_f, V_f \mapsto G \cup V \cup V_f \cup G_f$

**Observation 1:**  $G \cup V \cup G_f \cup V_f$  finite set of clauses (up to renaming of variables).

# The Ackermann class

---

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$G_f = G(c_1, \dots, c_n, f_i)$  ground clauses with function symbols

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$V, V \mapsto V \cup G$ ;  $V, G_f \mapsto G \cup G_f$ ;  $V, V_f \mapsto G \cup V \cup G_f \cup V_f$

$G_f, G_f \mapsto G_f$ ;  $G_f, V_f \mapsto G_f \cup G$ ;  $V_f, V_f \mapsto G \cup V \cup V_f \cup G_f$

**Observation 2:** No clauses with nested function symbols can be generated.

# The Ackermann Class

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## Conclusion:

Resolution (with implicit factorization) will always terminate if the input clauses are in the class defined before.

Resolution can be used as a decision procedure to check the satisfiability of formulae in the Ackermann class.